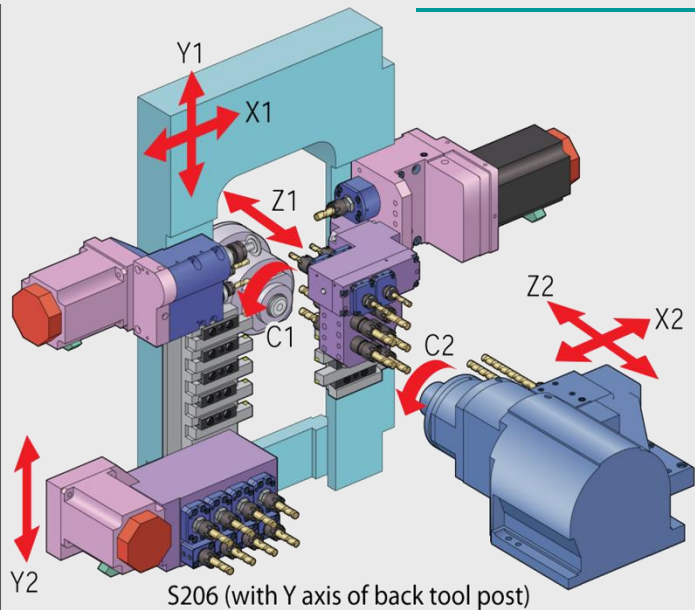


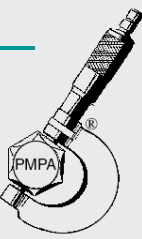
# Custom Macro Programming

Parametric Programming  
PMPA NTC 2013



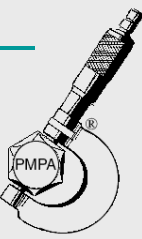
Presented by Ron Gainer & Dan Murphy  
Tsugami/Rem Sales

# Safety



- Every effort has been made to verify the information presented here is correct, however you should assume it is not and exercise caution when putting any of the examples presented here to use.

# Safety



- Macro programs can affect the motions of the machine tool. They can also be used to change coordinate data and parameter settings. Any of these changes can cause unexpected motion, crashes, and other machine malfunctions. Always exercise caution and follow safe procedures for proving out new programs or edits to existing programs.

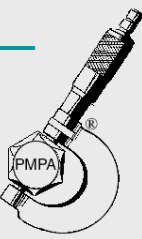
# Back Up Your Data



- Since Macro programming can be used to change parameters, offsets, and work coordinate data, make sure you have recently backed up your parameters, settings, work shifts, and offsets.



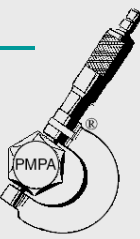
# Introduction



- This Seminar is meant to be an introduction to Custom Macro Programming. There is no way to cover all the material you should be aware of in such a short time period.
- Be sure to read the Custom Macro section of the manual for your particular control



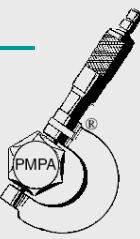
# Don't Be These Guys



**Manuals**

We don't need them. Attaaaaaaack!

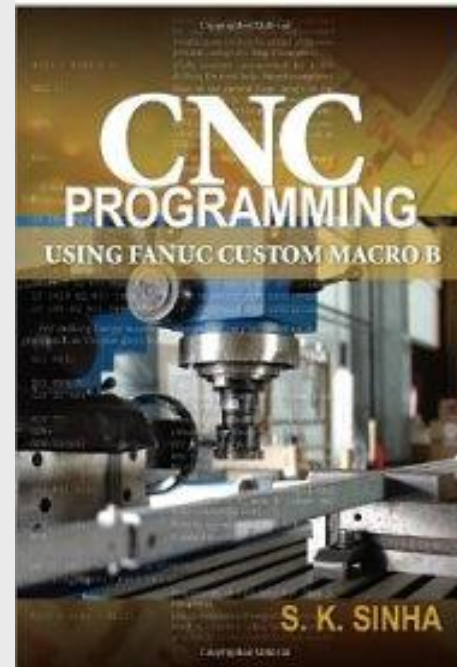
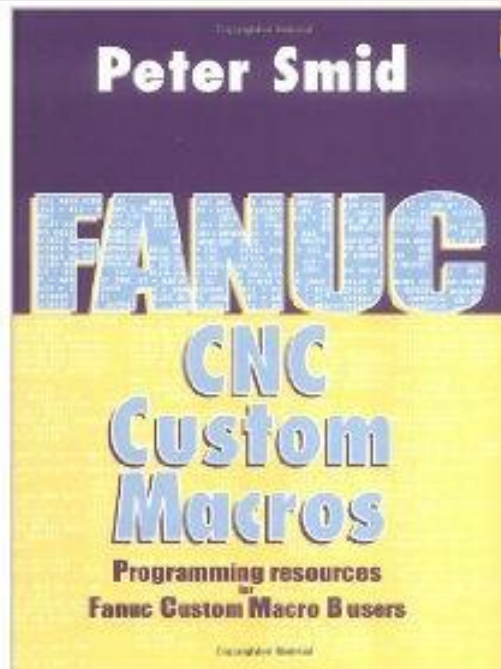
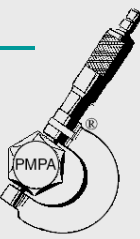
# Introduction



- This program concerns the application and use of “Custom Macro “B” on Fanuc controls. Particularly the Fanuc Oi
- The general concepts apply to almost any CNC control that has parametric programming capabilities.



# For Further Learning





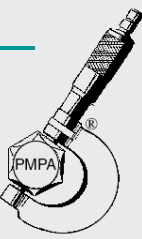
# For Further Learning



- Fanuc USA offers a course called “Programming Level II” that cover Macro B
- Call - 888-FANUC-US (888-326-8287)

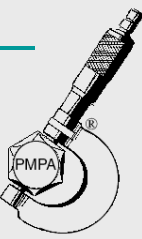


# Introduction



- Applications for Custom Macro Programming
  - Family of parts programming
  - Custom cycles
    - Canned or multiple repetition
  - Program complex motions
    - Parabolas, ellipses, etc
  - Use variables to adjust dimensions that offsets alone can't change
  - “Smart” programs
    - Macro programs can make decisions by using conditional statements
      - IF\_THEN, AND, OR, XOR, IF\_GOTO, GOTO, WHILE\_DO, END
    - Custom alarms and error traps

# Introduction



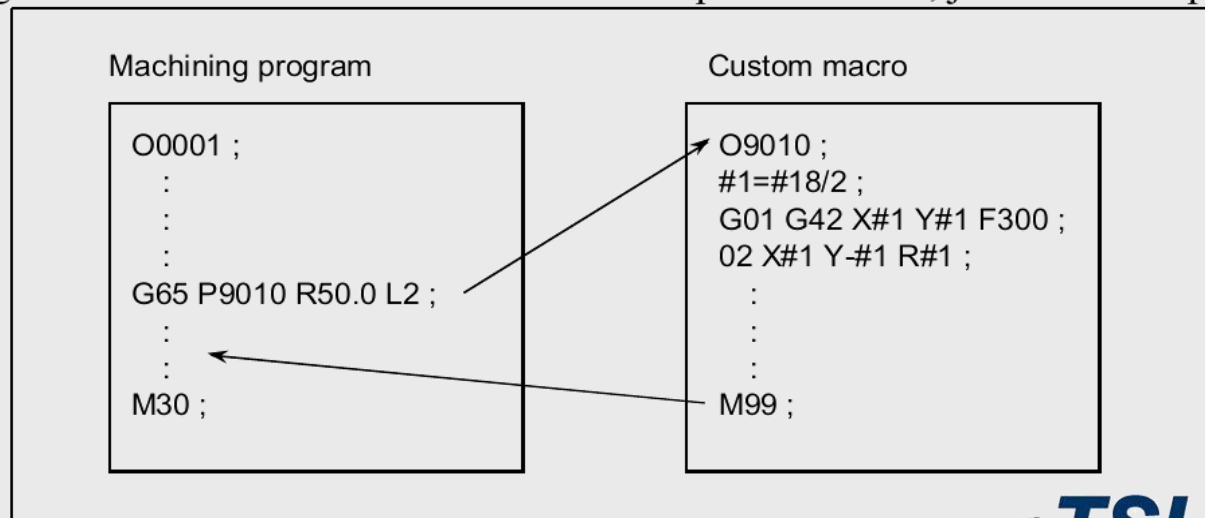
- Applications for Custom Macro Programming
  - Probing and in process gauging
  - Communication with external devices
    - Automation
    - Printers
    - Metrology devices
  - Machine status
    - Check if machine is in proper position
      - “Safe Start” macro
    - Check that offset data and work shifts are within range
    - Check other conditions
      - Cut off tool breakage on Swiss

# Uses for Macro Programming

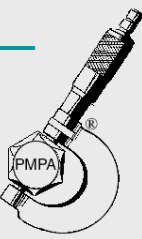


- Repetitive operations
  - Similar to using a sub program, but a macro will allow you to change conditions without having to edit multiple lines of code.
  - Example: Milling a pocket taking a number of passes. Using variables will allow you to change the DOC and number of passes without having to rewrite the sub routine.

A machining program can call a custom macro with a simple command, just like a subprogram.



# Uses for Macro Programming

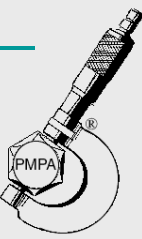


- Family of parts programming
  - One program can run all variations of a part on a tabled drawing.
- Variables are used in place of coordinate numbers in the program.

Conventional program  
G01 Z0.5 F0.003

Macro program  
G01 Z#501 F0.003

# Variables



- Variables are expressed in the program by a numerical value preceded by the pound sign
  - #100, #500
- The numerical value corresponds to a register on the macro page of the CNC display

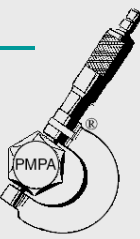
# Navigating to the Macro Variable Register



- 1<sup>st</sup> Press the Offset Key on Main Panel
- 2<sup>nd</sup> Press the right softkey that has the + symbol.

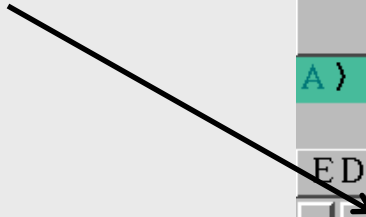
| OFFSET / WEAR |         | O5000 N00000 |        |               |  |
|---------------|---------|--------------|--------|---------------|--|
| NO.           | X       | Z            | R      | T             |  |
| W 001         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 002         | -0.0060 | 0.0000       | 0.0000 | 0             |  |
| W 003         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 004         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 005         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 006         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 007         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 008         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| RELATIVE      | U1      | 3.0320       | W1     | 2.5771        |  |
|               | V1      | 3.5967       |        |               |  |
| A) ^          |         |              |        |               |  |
|               |         | S            | 0 L    | 0%            |  |
| EDIT          | ****    | ***          | ***    | 06:25:14 MAIN |  |
| OFFSET        | SETTING | WORK         | (OPRT) | +             |  |

# Navigating to the Macro Variable Register



- 3<sup>rd</sup> Press the Macro Softkey.

| OFFSET / WEAR |         | 05000 N00000 |        |               |  |
|---------------|---------|--------------|--------|---------------|--|
| NO.           | X       | Z            | R      | T             |  |
| W 001         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 002         | -0.0060 | 0.0000       | 0.0000 | 0             |  |
| W 003         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 004         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 005         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 006         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 007         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| W 008         | 0.0000  | 0.0000       | 0.0000 | 0             |  |
| RELATIVE      | U1      | 3.0320       | W1     | 2.5771        |  |
|               | V1      | 3.5967       |        |               |  |
| A) ^          |         |              |        |               |  |
|               |         | S            | 0 L    | 0%            |  |
| EDIT          | ****    | ***          | ***    | 06:25:33 MAIN |  |
| MACRO         | MENU    | OPR          | (OPRT) | +             |  |





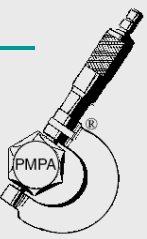
# Navigating to the Macro Variable Register



## ■ Macro Register Screen

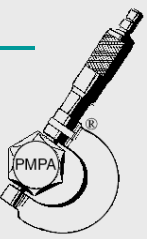
| CUSTOM MACRO |            |         |            | 05000 N00000 |      |
|--------------|------------|---------|------------|--------------|------|
| NO.          | DATA       | NO.     | DATA       |              |      |
| 00100        | DATA EMPTY | 00108   | DATA EMPTY |              |      |
| 00101        | DATA EMPTY | 00109   | DATA EMPTY |              |      |
| 00102        | DATA EMPTY | 00110   | DATA EMPTY |              |      |
| 00103        | DATA EMPTY | 00111   | DATA EMPTY |              |      |
| 00104        | DATA EMPTY | 00112   | DATA EMPTY |              |      |
| 00105        | DATA EMPTY | 00113   | DATA EMPTY |              |      |
| 00106        | DATA EMPTY | 00114   | DATA EMPTY |              |      |
| 00107        | DATA EMPTY | 00115   | DATA EMPTY |              |      |
| RELATIVE     | U1         | 3. 0320 | W1         | 2. 5771      |      |
|              | V1         | 3. 5967 |            |              |      |
| A) ^         |            |         |            |              |      |
| S 0 L 0%     |            |         |            |              |      |
| EDIT ****    |            | *** **  |            | 06:26:35     | MAIN |
| MACRO        | MENU       | OPR     |            | (OPRT)       | +    |

# Assigning a Value to a variable



- Values can be input manually into a variable register
- Values can also be assigned via the NC program
  - #510 = 1.5
  - #100 = #100 + 1
- Range is eight digits maximum
  - #510 = 12345678
  - #510 = 1234.5678
  - #510 = 12345.6789 will generate “TOO MANY DIGITS” alarm
- Decimal points are not considered digits however leading zeros are
  - #510 = 1234.5678 is ok
  - #510 = 0.12345678 is too many digits

# Variables



- Variables Can Only be Mathematical Quantities (numbers)
  - ❑ Can not have values of “Yes” or “No”
  - ❑ Can’t be “True” or “False”
  - ❑ Can’t be letters

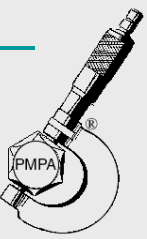
# A Variable Can Be Made Conditional



```
O1234;  
#10 = 60;  
#20 = 30;  
IF [#10 GT #20] THEN #1 = #10 - #20;  
M#1;
```

(Variable 10 is assigned a value of 60)  
(Variable 20 is assigned a value of 30)  
(If the value of variable 10 is greater  
than variable 20 = "True" condition  
So the value of variable 1 = 30)

# Expressions



- An expression is either a mathematical statement or a conditional statement.

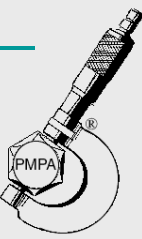
**Conditional Statement** – IF [#103 EQ 0] GOTO5

If variable number 103 is equal to zero go to line N5

**Mathematical Statement** - #107 = #106 - #105

Subtract variable number 105 from variable number 106 and place the result in variable number 107

# Expressions



- Enclosing a value within brackets [ ] is considered a macro expression
  - G00 X[.5]
  - G01 X[.5-.2]
- Brackets also denote the hierarchy of operations

IF [#1 LT #2] GOTO 99      (Compare #1 to #2, then if true go to line N99)

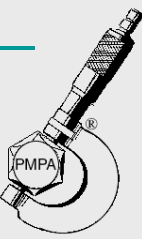
#100 = #20 - [#10 \* 2]      (Multiply #10 by 2, then subtract the result from #20)

# Expressions



- A macro variable can also be represented as an expression
  - $\#[\#100]$
  - $\#[\#1001-1]$
  - $\#[\#6/2]$

# Substituting Variable Values in Program



- All NC “words” can have a variable as their value, except “O” (program number) and “N” (sequence number)

Coordinate word examples:

#100 = 1.2;

G00 X#100; (same as G00 X1.2)

G-codes

#10 = 00

G#10 X1.2 (same as G00)

S-codes

#100 = 2500;

G97 M03 S#100; (same as M03 S2500)

O#100 (Illegal)

F-codes

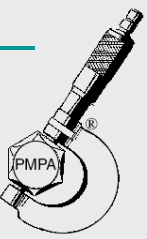
#100 = .003;

G99 G01 X.5 F#100; (same as F0.003)

N#100 (Illegal)

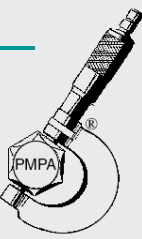


# Substituting Variable Values in Program



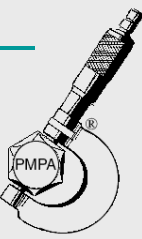
- **Caution Must Be Exercised**
  - Using variables with G-codes is not good practice
  - Whenever variables are used in place of coordinate values and/or NC words, unexpected machine movement can result

# Substituting Variable Values in Program



- Understand how real numbers and integers are treated by the CNC control
  - Real numbers are any number rational or irrational
    - Real numbers include integers
    - 1.25, -.3765, 5, -10 are all real numbers
  - Integers are whole numbers
    - 2500, 3, 20
    - Numbers with decimals are not integers i.e. 1.25
  - Some NC words only allow integers
    - S-commands: M03 S2000 is ok, M03 S2000.5 is not

# Substituting Variable Values in Program



- Understand how real numbers and integers are treated by the CNC control
- Some NC words only allow integers
  - M-codes: M05 is acceptable M05.5 is not
- Use of brackets can in some cases round to nearest integer
- In some cases variables will automatically be rounded
- Always refer to the manual to eliminate any doubt

Example:

M03 S1001.5 (an illegal statement as S-codes have to be integers)

Example:

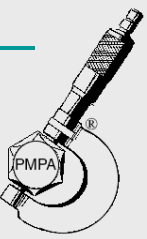
M03 S[1000.5] (will be treated as M03 S1001)

Example:

#1=1000.5

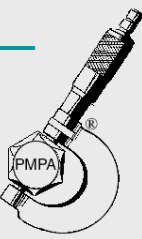
M03 S#1 (will be treated as M03 S1001)

# Substituting Variable Values in Program



- G-codes present a special challenge
  - As a rule **NEVER USE VARIABLES TO EXPRESS THE VALUE OF A G-CODE**
- Despite being able to use real numbers with G-codes (G12.1, G52.1, etc) the control will round up a variable from one place to the right of the decimal and treat the value as an integer only

# Variable That Contains No Value



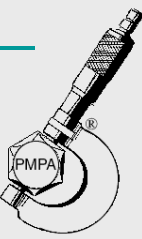
- A variable with no value is considered “Null”
  - Null does not necessarily equal zero
- When a variable of null value is used, the control will, in most cases, ignore the command
- This can be dangerous

Example:

Variable 100 equals null

G97 M03 S#100 (The spindle will start clockwise at the last commanded value)

# Safety



- An operator was killed by a boring head on a machining center where the RPM was specified by a variable
- The variable was set to null, so the last programmed RPM was used by the control
- The RPM exceeded the rating of the boring head
- The head came apart and the operator was struck by the debris and killed

# Safety



- If you are using a variable and know that if the value is set outside a certain range that danger exists, then add safety checks to your code without fail.

Example: Spindle can run up to 6000 RPM but the boring head in use is rated to 2,500RPM

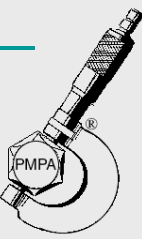
```
#100 = 6000;
```

```
M03 S#100; ← (RPM = 6000, Boring Head Blows Up)
```

```
#100 = 6000;
```

```
IF [#100 GT 2500] THEN #3000=1 (RPM TOO HIGH); ← (Conditional statement that  
M03 S#100; checks that the RPM does not  
exceed 2500. If it does  
“ALARM 3001 RPM TOO HIGH”  
will be generated)
```

# Variable #0



- #0 is a read only System variable permanently set to null so it can be used for comparison
- #0 can also be used to set another variable to null
  - #1 = #0 sets #1 to null
  - #0 = #1 illegal statement because #0 is read only
- In the previous example the RPM check does not prevent a null value being used which would cause the spindle to run at the last programmed RPM.
  - In the case of the boring head, this is what happened
- #0 can be used in a safety check below:

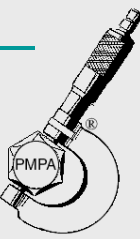
```
#100 = #0;
```

```
IF [#100 GT 2500] THEN #3000=1 (RPM TOO HIGH);
```

```
IF [#100 EQ #0] THEN #3000=2 (NO RPM SET IN #100); ← ALARM 3002 will be  
G97 M03 S#100; generated.
```



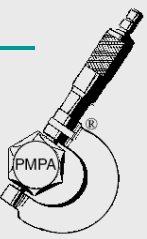
# How Null Variables Behave in Arithmetic



- All variables are assumed null in these examples
- In math operations null (no value) is looked at as zero

|                   |   |
|-------------------|---|
| $\#2 = \#1;$      | $\#2$ remains null because there is no math or evaluation in this statement                       |
| $\#2 = [\#1];$    | $\#2$ remains null. Even though the brackets make this an expression no math or evaluation occurs |
| $\#2 = \#1 + \#1$ | $\#2$ will equal zero. No value plus no value has a value of zero                                 |
| $\#2 = \#1 * 5$   | $\#2$ will equal zero   |

# How Null Variables Behave in Expressions



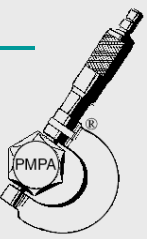
- In comparative expressions EQ (equal to) and NE (not equal to), null variables are not considered the same as 0

Examples - #1 = null

|            |  |
|------------|--|
| [#1 EQ 0]  | False, null variable is not equal to 0 |
| [#1 NE 0]  | True, null variable is not equal to 0  |
| [#1 EQ #0] | True, #0 value is always null          |
| [#2 NE #0] | False, #0 value is always null         |

Conditional Statement – IF [#1 EQ 0] THEN (some action)

# How Null Variables Behave in Expressions



- In all other conditional expressions a null value variable is considered 0
  - LT – less than, LE - less than or equal to
  - GT – Greater than, GE - Greater than or equal to

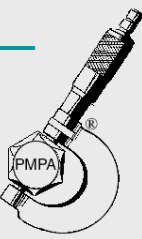
|           |                                |
|-----------|--------------------------------|
| [#1 LT 0] | False, 0 is not less than 0    |
| [#1 LE 0] | True, 0 is equal to 0          |
| [#1 GT 0] | False, 0 is not greater than 0 |
| [#1 GE 0] | True, 0 is equal to zero       |

# Using Variables

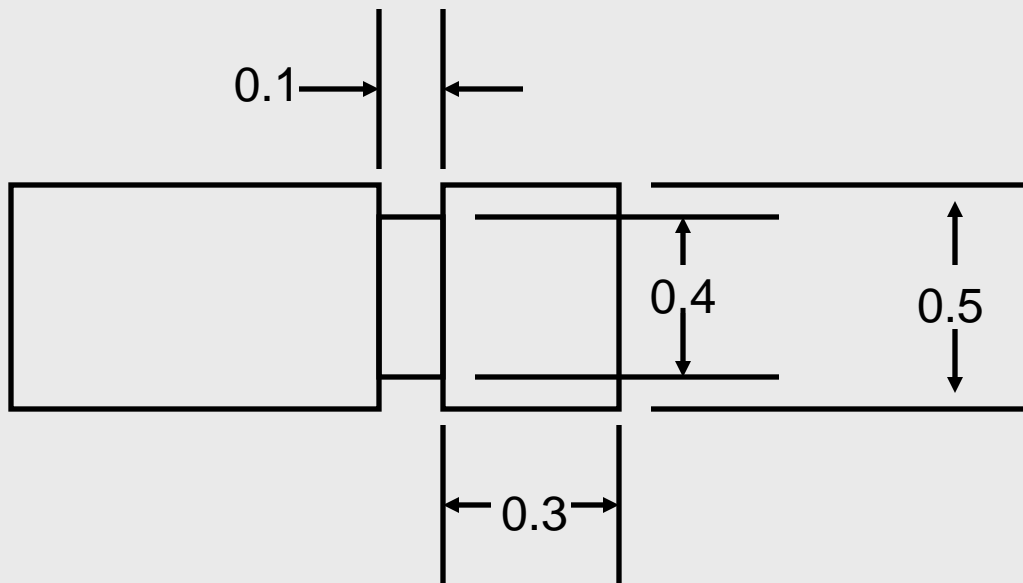


- At this point you have enough knowledge to use macro variables in two of the most common ways.
  - Adjusting feature size
  - Family of part programming

# Adjusting Feature Size

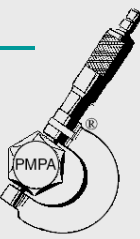


- Width of a groove
  - 0.093" groove tool width



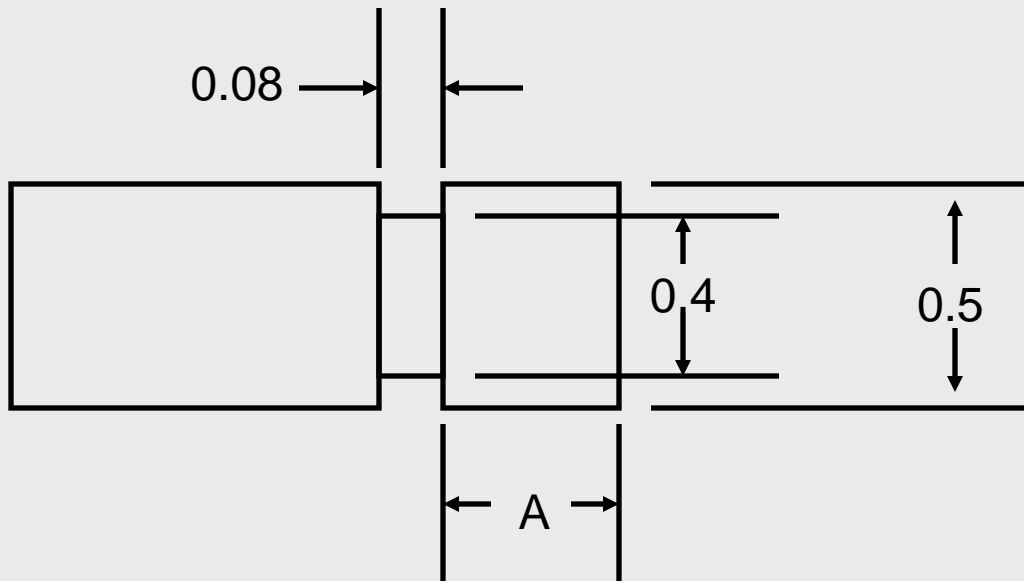
T1414;  
G96 M03 S200;  
G50 S5000;  
G00 X.55 Z.3;  
G99 G01 X.4 F.003  
G00X.55  
Z[.307+#514]  
G01 X.4  
G00X1.18 T0

# Family of Part Programming



- Variable feature location
  - 0.08" groove tool width

```
T1414;  
G96 M03 S200;  
G00 X.55 Z.#514;  
G99 G01 X.4 F.003  
G00X1.18 T0
```



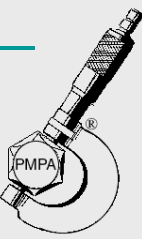
| PN | A  |
|----|----|
| -1 | .3 |
| -2 | .4 |
| -3 | .5 |

# Types of Variables



- Read only permanent value (#0, 3100-3102)
- Local variables (#1 through #33)
- Common variables (#100 through #199)
- Permanent common variable (#500-#599)
  - Can also be made “read only” by parameter setting
- System variables

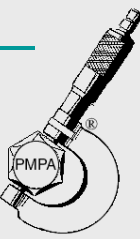
# Local Variables (#1 - #33)



- A local variable is used locally as opposed to globally, that is to say that a local variable called by one macro call at a certain time is different from the same variable called at another time by a different macro call.
- Local variables are used to pass arguments from a macro call
- Variable number #1-#33 are tied to letter addresses in the macro call



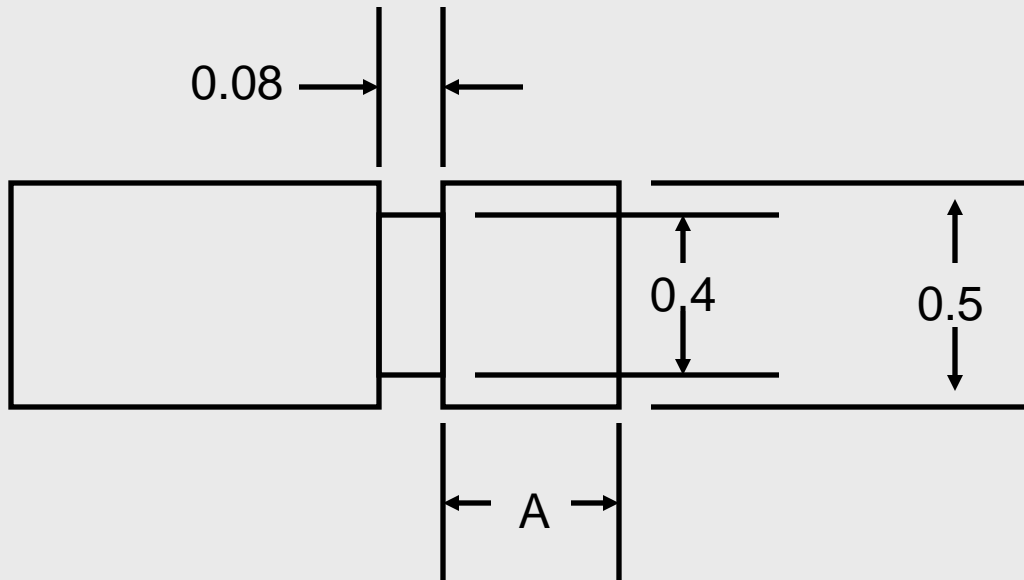
# Macro Call for Variable Feature



## ■ Variable feature location

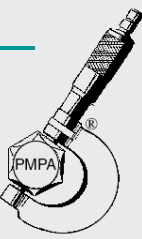
Call from main program  
G65 P9014 A.3

O9014  
T1414;  
G97 M03 S2000;  
G00 X.55 Z.#1;  
G99 G01 X.4 F.003  
G00X1.18 T0  
M99



| PN | A  |
|----|----|
| -1 | .3 |
| -2 | .4 |
| -3 | .5 |

# Macro Argument Correlation



- Argument specification I

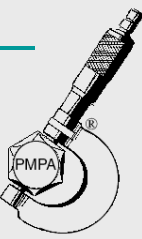
| Address | Variable number |
|---------|-----------------|
| A       | #1              |
| B       | #2              |
| C       | #3              |
| D       | #7              |
| E       | #8              |
| F       | #9              |
| H       | #11             |

| Address | Variable number |
|---------|-----------------|
| I       | #4              |
| J       | #5              |
| K       | #6              |
| M       | #13             |
| Q       | #17             |
| R       | #18             |
| S       | #19             |

| Address | Variable number |
|---------|-----------------|
| T       | #20             |
| U       | #21             |
| V       | #22             |
| W       | #23             |
| X       | #24             |
| Y       | #25             |
| Z       | #26             |

- Addresses G, L, N, O, and P cannot be used in arguments.
- Addresses that need not be specified can be omitted. Local variables corresponding to an omitted address are set to null.
- Addresses do not need to be specified alphabetically. They conform to word address format. I, J, and K need to be specified alphabetically, however. Argument specification I is always used for I, J, and K by setting bit 7 (IJK) of parameter No. 6008 to 1

# Variables



## - Range of variable values

Local and common variables can have a value in the following ranges. If the result of calculation exceeds the range, an alarm PS0111 is issued.

When bit 0 (F0C) of parameter No.6008 = 0

Maximum value: approx.  $\pm 10^{308}$

Minimum value: approx.  $\pm 10^{-308}$

Numeric data handled by a custom macro conforms to the IEEE standard and is handled as a double-precision real number. An error resulting from operation depends on the precision.

When bit 0 (F0C) of parameter No.6008 = 1

Maximum value: approx.  $\pm 10^{47}$

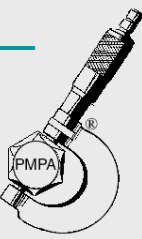
Minimum value: approx.  $\pm 10^{-29}$

# Common Variables #100-#199



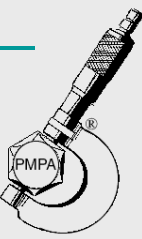
- These variables are global. They have the same value in any macro call.
- These variable are read/write unless protected by parameter change
  - Parameter 6031 and 6032 on FS OiD
- These variables are reset to null upon power down

# Common Variables #500-#999



- These variables are global. They have the same value in any macro call.
- These variable are read/write unless protected by parameter change
  - Parameter 6031 and 6032 on FS OiD
- These variables will retain their values upon power down, reset, etc.
- These variables are preferred when input from the operator is required
  - Feature size adjustment
  - Family of parts
  - Tool life management count values

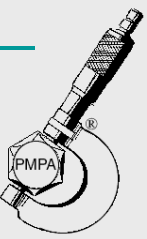
# System Variables



- Variable whose usage does not vary in the system
  - The variable's address will always return the same information, though the value will vary
- System variables can be Read only, Read/Write, or Write only depending on the nature of the variable
- System Constants are system variables whose values are fixed. They are Read only.

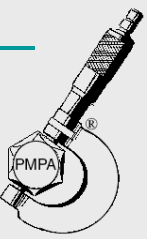
| Constant number | Constant name | Description  |
|-----------------|---------------|--|
| #0, #3100       | [#_EMPTY]     | Null   |
| #3101           | [#_PI]        | Circular constant $\pi = 3.14159265358979323846$       |
| #3102           | [#_E]         | Base of natural logarithm $e = 2.71828182845904523536$ |

# Variables



- Omission of the decimal point
  - Decimal points can be left out when the value is an integer.
    - #1=123 will be treated the same as #1=123.0000

# Specifying a Common Variable by its Name



- You can name common variables using the SETVN command.
  - This is useful in that a name that correlates to the variables value is more easily recognizable in the program than a variable number.

Examples:

X[#POS1] Y[#POS2] ; : Specifying a position by the variable name

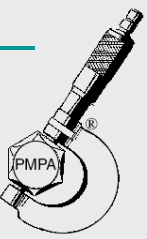
[#POS1] = #100+#101 ; : Executing a assignment statement by the variable name

#[100+[#ABS]] = 500 ; : Same as above (by a variable number)

#500 = [1000+[#POS2]\*10] ; : Reading a variable by a variable name



# SETVN Command



- For the 50 common variables, #500 to #549, a name of up to eight characters can be specified by using a command as shown below.

**SETVN n [VAR500, VAR501, VAR502,.....] ;**

n represents the starting number of a common variable for which the name is specified.

VAR500 is the variable name of variable n, VAR501 is the variable name of variable n+1, and VAR502 is the variable name of variable number n+2, and so on. Each string is delimited by a comma (.). All codes that can be used as meaningful information in a program except control in, control out, [, ], EOB, EOR, and : (colon in a program number) can be used. However, each name must begin with an alphabetical character. Variable names are not cleared on switch-off.

Specifying a set variable name allows reading from or writing to the common variable. The command must be specified in the form [#common-variable-name] such as [#VAR500].

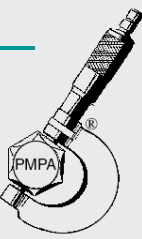
[Example] SETVN 510[TOOL\_NO, WORK\_NO, COUNTER1, COUNTER2];

The command above names the variables as follows.

| Variable | Name      |
|----------|-----------|
| #510     | #TOOL_NO  |
| #511     | #WORK_NO  |
| #512     | #COUNTER1 |
| #513     | #COUNTER2 |

The names specified by the command can be used in a program. For example, when 10 is assigned to #510, the expression [#TOOL\_NO]=10; can be used instead #510=10;.

# System Variable Names

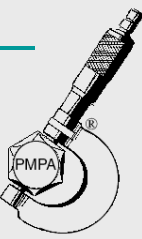


- Names can be used with system variables
- The name is fixed in the control and can not be changed

Example: Wear Offsets on a T Control

| Variable number | Variable name | Position information       | Read operation during movement |
|-----------------|---------------|----------------------------|--------------------------------|
| #5081           | [_TOFSWX]     | X-axis tool offset value   | Disabled                       |
| #5082           | [_TOFSWZ]     | Z-axis tool offset value   |                                |
| #5083           | [_TOFSWY]     | Y-axis tool offset value   |                                |
| #5084           | [_TOFS[4]]    | 4th axis tool offset value |                                |
| #5085           | [_TOFS[5]]    | 5th axis tool offset value |                                |

# System Variable Overview:



System variables allow you to determine and set machine information. This would include machine position, skip signal position, work & tool offsets. You can also read current “G”, “M”, “S”, “T”, and “H” codes.

There are also System Variables for programmable inputs and outputs.

# Displaying System Variables



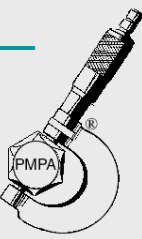
- Unlike common variables, there is no page on the control that will display the value of system variables.
- You can see the value of a system variable by returning it to a common variable

For example to see the system variable for time, command:

```
#100=#3012
```

The time will then be stored in variable 100 as Hour/Min/Sec

# List of System Variables



n represents a subscript.

R, W, and R/W are attributes of a variable and indicate read-only, write-only, and read/write enabled, respectively.

## - Interface signals

| System variable number | System variable name | Attribute | Description   |
|------------------------|----------------------|-----------|---|
| #1000-#1031            | [_UI[n]]             | R         | Interface input signals (BIT), UI000-UI031<br>NOTE) Subscript n represents a BIT position (0-31).   |
| #1032-#1035            | [_UIL[n]]            | R         | Interface input signals (LONG), UI000-UI031/ UI100-UI131/<br>UI200-UI231/UI300-UI331<br>NOTE) Subscript n (0-3): 0 = UI000-UI031, 1 =<br>UI100-UI131,<br>2 = UI200-231, 3 = UI300-UI331 |
| #1100-#1131            | [_UO[n]]             | R/W       | Interface output signals (BIT), UO000-UO031<br>NOTE) Subscript n represents a BIT position (0-31).  |
| #1132-#1135            | [_UOL[n]]            | R/W       | Interface output signals (LONG), UO000-UO031/<br>UO100-UO131/UO200-UO231/UO300-UO331<br>NOTE) Subscript n (0-3): 0 = UO000-UO031,<br>1 = UO100-UO131,<br>2 = UO200-231, 3 = UO300-UO331 |

# System Variable Overview: Descriptions



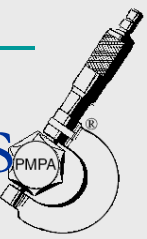
#1000-#1035=Supplied inputs to CNC

Example: Coolant Off Switch has a supplied input in machine ladder.

```
IF[#1000EQ1]GOTO881
```

```
N881#3000=1(COOLANT OFF ALARM)
```

# System Variable Overview: Descriptions



#1100-#1135=Programmable outputs to CNC

Example: Hydraulic support activated by macro output

#1100=1(CLOSE SUPPORT)

# System Variable Overview: Descriptions



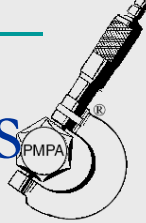
## #2000-#2999 Tool Compensation Variables

These values vary depending on the number of offsets and the type of tool offset memory your control has.

They are read/write capable.



# System Variable Overview: Descriptions



Tool Offset system example:

## - Tool compensation value

**T**

Without tool geometry/wear compensation memory (bit 6 (NGW) of parameter No. 8136 is 1)

| System variable number       | System variable name | Attribute | Description   |
|------------------------------|----------------------|-----------|---|
| #2001-#2064<br>#10001-#10200 | [_OFSX[n]]           | R/W       | X-axis compensation value (*1)<br>Note)Subscript n represents a compensation number (1 to 64).<br>The numbers on the left are also allowed.<br>Note)Subscript n represents a compensation number (1 to 200).      |
| #2101-#2164<br>#11001-#11200 | [_OFSZ[n]]           | R/W       | Z-axis compensation value (*1)<br>Note)Subscript n represents a compensation number (1 to 64).<br>The numbers on the left are also allowed.<br>Note)Subscript n represents a compensation number (1 to 200).      |
| #2201-#2264<br>#12001-#12200 | [_OFSR[n]]           | R/W       | Tool nose radius compensation value<br>Note)Subscript n represents a compensation number (1 to 64).<br>The numbers on the left are also allowed.<br>Note)Subscript n represents a compensation number (1 to 200). |
| #2301-#2364<br>#13001-#13200 | [_OFST[n]]           | R/W       | Virtual tool tip T position<br>Note)Subscript n represents a compensation number (1 to 64).<br>The numbers on the left are also allowed.<br>Note)Subscript n represents a compensation number (1 to 200).         |
| #2401-#2449<br>#14001-#14200 | [_OFSY[n]]           | R/W       | Y-axis compensation value (*1)<br>Note)Subscript n represents a compensation number (1 to 49)<br>The numbers on the left are also allowed.<br>Note)Subscript n represents a compensation number (1 to 200).       |

(\*1) X-axis: X-axis of basic three axes, Z-axis: Z-axis of basic three axes, Y-axis: Y-axis of basic three axes

# System Variable Overview: Descriptions



| System variable number | System variable name | Attribute | Description   |
|------------------------|----------------------|-----------|---|
| #3003                  | [_CNTL1]             | R/W       | Enable or disable the suppression of single block stop.<br>Enable or disable the waiting of the auxiliary function completion signal. |
| #3003 bit0             | [#_M_SBK]            | R/W       | Enable or disable the suppression of single block stop.   |
| #3003 bit1             | [#_M_FIN]            | R/W       | Enable or disable waiting for the auxiliary function completion signal.   |
| #3004                  | [_CNTL2]             | R/W       | Enable or disable feed hold.<br>Enable or disable feedrate override.<br>Enable or disable exact stop check.                           |
| #3004 bit0             | [#_M_FHD]            | R/W       | Enable or disable feed hold.  |
| #3004 bit1             | [#_M_OV]             | R/W       | Enable or disable feedrate override.  |
| #3004 bit2             | [#_M_EST]            | R/W       | Enable or disable exact stop check.   |
| #3005                  | [#_SETDT]            | R/W       | Read/write setting data.  |
| #3006                  | [#_MSGSTP]           | W         | Stop with a message.  |
| #3007                  | [#_MRIMG]            | R         | Status of a mirror image (DI and setting)   |
| #3008                  | [#_PRSTR]            | R         | Restarting/not restarting a program   |

## - Time

| System variable number | System variable name | Attribute | Description        |
|------------------------|----------------------|-----------|--------------------|
| #3011                  | [#_DATE]             | R         | Year/Month/Date    |
| #3012                  | [#_TIME]             | R         | Hour/Minute/Second |

## - Number of parts

| System variable number | System variable name | Attribute | Description              |
|------------------------|----------------------|-----------|--------------------------|
| #3901                  | [#_PRTSA]            | R/W       | Total number of parts    |
| #3902                  | [#_PRTSN]            | R/W       | Number of required parts |

# System Variable Overview: Descriptions



## Commonly used variables:

- #3000 is used to generate a macro alarm.  
#3000=1 (VALUE A TOO LARGE) This will stop the machine in alarm status with alarm 3001 (VALUE A TOO LARGE) Message displayed on the screen. W
- #3006 is used to stop the machine in feed hold status with a message. W  
#3006=1 (INSTALL SUPPORT).
- #3007=Mirror Image status R

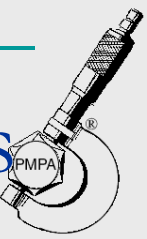
# System Variable Overview: Descriptions



## Commonly used variables:

- #3011 Date (Year/Month/Date) R
- #3012 Time (Hour/Minute/Second) R
- #3901 Total Number of Parts R/W
- #3902 Number of Required Parts R/W
- #4000 Main Program # R

# System Variable Overview: Descriptions



## Modal Information:

- #4001-#4030 Model G-code information (R)

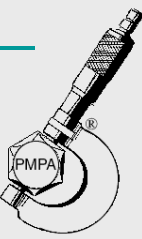
Example #4001=Active G-code of Group 1

Group 1 G-codes include:

G00,G01,G02,G03,G32.

#100=#4001 Loads the current active code to #100.

# G-Code Groups

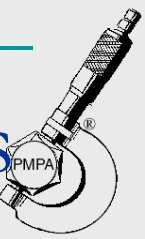


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Table 3.2 (a) G code list

| G code system   |                 |                 | Group | Function  |
|-----------------|-----------------|-----------------|-------|---|
| A               | B               | C               |       |   |
| G00             | G00             | G00             | 01    | Positioning (Rapid traverse)                            |
| G01             | G01             | G01             |       | Linear interpolation (Cutting feed)                     |
| G02             | G02             | G02             |       | Circular interpolation CW or helical interpolation CW   |
| G03             | G03             | G03             |       | Circular interpolation CCW or helical interpolation CCW |
| G04             | G04             | G04             | 00    | Dwell   |
| G05.4           | G05.4           | G05.4           |       | HRV3 on/off   |
| G07.1<br>(G107) | G07.1<br>(G107) | G07.1<br>(G107) |       | Cylindrical interpolation                               |
| G08             | G08             | G08             |       | Advanced preview control                                |
| G09             | G09             | G09             |       | Exact stop  |
| G10             | G10             | G10             |       | Programmable data input                                 |
| G11             | G11             | G11             |       | Programmable data input mode cancel                     |
| G12.1<br>(G112) | G12.1<br>(G112) | G12.1<br>(G112) | 21    | Polar coordinate interpolation mode                     |
| G13.1<br>(G113) | G13.1<br>(G113) | G13.1<br>(G113) |       | Polar coordinate interpolation cancel mode              |
| G17             | G17             | G17             | 16    | XpYp plane selection                                    |
| G18             | G18             | G18             |       | ZpXp plane selection                                    |
| G19             | G19             | G19             |       | YpZp plane selection                                    |
| G20             | G20             | G70             | 06    | Input in inch   |
| G21             | G21             | G71             |       | Input in mm   |
| G22             | G22             | G22             | 09    | Stored stroke check function on                         |
| G23             | G23             | G23             |       | Stored stroke check function off                        |
| G25             | G25             | G25             | 08    | Spindle speed fluctuation detection off                 |
| G26             | G26             | G26             |       | Spindle speed fluctuation detection on                  |
| G27             | G27             | G27             | 00    | Reference position return check                         |
| G28             | G28             | G28             |       | Return to reference position                            |
| G30             | G30             | G30             |       | 2nd, 3rd and 4th reference position return              |
| G31             | G31             | G31             |       | Skip function   |

# System Variable Overview: Descriptions



## Modal Information Preceding Block (R)

- #4102= B-Code
- #4107= D-Code
- #4108= E-Code
- #4109= F-Code
- #4111= H-Code
- #4113= M-Code
- #4114= Sequence #
- #4115= Program #

# System Variable Overview: Descriptions

## Modal Information Preceding Block(R)



- #4119= S-Code
- #4120= T-Code
- #4130= Additional Coordinate System
  
- #4201 Starts Over with Current Block G-code Group 1 Modal Information.



# System Variable Overview: Descriptions

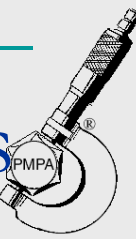


## Position Information:

| System variable number | System variable name | Attribute | Description  |
|------------------------|----------------------|-----------|--|
| #5001-#5005            | [_ABSIO[n]]          | R         | End point position of the previous block (workpiece coordinate system)<br>Note) Subscript n represents an axis number (1 to 5) |
| #5021-#5025            | [_ABSMT[n]]          | R         | Specified current position (machine coordinate system)<br>Note) Subscript n represents an axis number (1 to 5).                |

| System variable number | System variable name | Attribute | Description   |
|------------------------|----------------------|-----------|---|
| #5041-#5045            | [_ABSOT[n]]          | R         | Specified current position (workpiece coordinate system)<br>Note) Subscript n represents an axis number (1 to 5). |
| #5061-#5065            | [_ABSKP[n]]          | R         | Skip position (workpiece coordinate system)<br>Note) Subscript n represents an axis number (1 to 5).              |

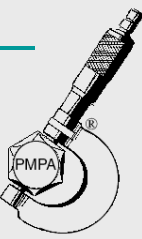
# System Variable Overview: Descriptions



## Work Offsets:

| System variable number | System variable name | Attribute | Description  |
|------------------------|----------------------|-----------|--|
| #5201-#5205            | [_WZCMN[n]]          | R/W       | External workpiece origin offset value<br>Note)Subscript n represents an axis number (1 to 5). |
| #5221-#5225            | [_WZG54[n]]          | R/W       | G54 workpiece origin offset value<br>Note)Subscript n represents an axis number (1 to 5).      |
| #5241-#5245            | [_WZG55[n]]          | R/W       | G55 workpiece origin offset value<br>Note)Subscript n represents an axis number (1 to 5).      |
| #5261-#5265            | [_WZG56[n]]          | R/W       | G56 workpiece origin offset value<br>Note)Subscript n represents an axis number (1 to 5).      |
| #5281-#5285            | [_WZG57[n]]          | R/W       | G57 workpiece origin offset value<br>Note)Subscript n represents an axis number (1 to 5).      |
| #5301-#5305            | [_WZG58[n]]          | R/W       | G58 workpiece origin offset value<br>Note)Subscript n represents an axis number (1 to 5).      |
| #5321-#5325            | [_WZG59[n]]          | R/W       | G59 workpiece origin offset value<br>Note)Subscript n represents an axis number (1 to 5).      |

# Arithmetic and Logic



- Various operations involving arithmetic and/or logic can be performed on variables

$\#i = \langle \text{expression} \rangle$

## <Expression>

The expression to the right of the arithmetic and logic operation contains constants and/or variables combined by a function or operator. Variables  $\#j$  and  $\#k$  below can be replaced with a constant. If a constant used in an expression has no decimal point, it is assumed to end with a decimal point.

Table 14.3 (a) Arithmetic and logic operation

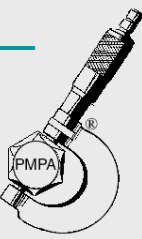
| Type of operation                  | Operation  | Description   |
|------------------------------------|--|---|
| <1> Definition or replacement      | $\#i = \#j$  | Definition or replacement of a variable   |
| <2> Addition-type operations       | $\#i = \#j + \#k$<br>$\#i = \#j - \#k$<br>$\#i = \#j \text{ OR } \#k$<br>$\#i = \#j \text{ XOR } \#k$  | Addition<br>Subtraction<br>Logical OR (bit by bit of 32 bits)<br>Exclusive OR (bit by bit of 32 bits)   |
| <3> Multiplication-type operations | $\#i = \#j * \#k$<br>$\#i = \#j / \#k$<br>$\#i = \#j \text{ AND } \#k$<br>$\#i = \#j \text{ MOD } \#k$ | Multiplication<br>Division<br>Logical AND (bit by bit of 32 bits)<br>Remainder (A remainder is obtained after $\#j$ and $\#k$ are rounded to their nearest whole numbers. When $\#j$ is a negative value, $\#i$ is assumed to be a negative value.) |

# Arithmetic and Logic



| Type of operation | Operation                    | Description  |
|-------------------|------------------------------|--|
| <4> Functions     | #i=SIN[#j]                   | Sine (in degrees)                                  |
|                   | #i=COS[#j]                   | Cosine (in degrees)                                |
|                   | #i=TAN[#j]                   | Tangent (in degrees)                               |
|                   | #i=ASIN[#j]                  | Arc sine   |
|                   | #i=ACOS[#j]                  | Arc cosine   |
|                   | #i=ATAN[#j]                  | Arc tangent (one argument), ATN can also be used.  |
|                   | #i=ATAN[#j]/[#k]             | Arc tangent (two arguments), ATN can also be used. |
|                   | #i=ATAN[#j],#k]              | Arc tangent (two arguments), ATN can also be used. |
|                   | #i=SQRT[#j]                  | Square root, SQR can also be used.                 |
|                   | #i=ABS[#j]                   | Absolute value                                     |
|                   | #i=BIN[#j]                   | Conversion from BCD to binary                      |
|                   | #i=BCD[#j]                   | Conversion from binary to BCD                      |
|                   | #i=ROUND[#j]                 | Rounding off, RND can also be used.                |
|                   | #i=FIX[#j]                   | Rounding down to an integer                        |
|                   | #i=FUP[#j]                   | Rounding up to an integer                          |
|                   | #i=LN[#j]                    | Natural logarithm                                  |
|                   | #i=EXP[#j]                   | Exponent using base e (2.718...)                   |
| #i=POW[#j,#k]     | Power (#j to the #kth power) |  |
| #i=ADP[#j]        | Addition of a decimal point  |  |

# Arithmetic and Logic



## Explanation

### - Angle units

The units of angles used with the SIN, COS, ASIN, ACOS, TAN, and ATAN functions are degrees. For example, 90 degrees and 30 minutes is represented as 90.5 degrees.

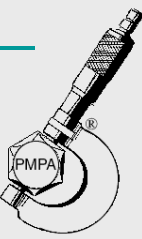
### - **ARCSIN #i = ASIN[#j];**

- The solution ranges are as indicated below:  
When the bit 0 (NAT) of parameter No.6004 is set to 0: 270° to 90°  
When the bit 0 (NAT) of parameter No.6004 is set to 1: -90° to 90°
- When #j is beyond the range of -1 to 1, an alarm PS0119 is issued.
- A constant can be used instead of the #j variable.

### - **ARCCOS #i = ACOS[#j];**

- The solution ranges from 180° to 0°.
- When #j is beyond the range of -1 to 1, an alarm PS0119 is issued.
- A constant can be used instead of the #j variable.

# Arithmetic and Logic



## - **ARCTAN #i = ATAN[#j]/[#k]; (two arguments)**

- $ATAN[#j, \#k]$  is equivalent to  $ATAN[#j]/[\#k]$ .
- When point ( $\#k, \#j$ ) on plane X-Y is given, this function returns the value of the arc tangent for the angle made by the point.
- A constant can be used instead of the  $\#j$  variable.
- The solution ranges are as follows:

When the bit 0 (NAT) of parameter No.6004 is set to 0:  $0^\circ$  to  $360^\circ$

Example:

When  $\#1 = ATAN[-1]/[-1]$ ; is specified,  $\#1$  is 225.0.

When the bit 0 (NAT) of parameter No.6004 is set to 1:  $-180^\circ$  to  $180^\circ$

Example:

When  $\#1 = ATAN[-1]/[-1]$ ; is specified,  $\#1$  is -135.0.

## - **ARCTAN #i = ATAN[#j]; (one argument)**

- When ATAN is specified with one argument, this function returns the main value of arc tangent ( $-90^\circ \leq ATAN[\#j] \leq 90^\circ$ ). In other word, this function returns the same value as ATAN in calculator specifications.
- To use this function as the dividend of a division, be sure to enclose it with brackets ([ ]). If this function is not enclosed,  $ATAN[\#j]/[\#k]$  is assumed.

Example:

$\#100 = [ATAN[1]]/10$  ; : Divides ATAN with one argument by 10.

$\#100 = ATAN[1]/[10]$  ; : Executes ATAN with two arguments.

$\#100 = ATAN[1]/10$  ; : Assumes ATAN with two arguments, but issues an alarm PS1131 because the X coordinate specification is not enclosed with brackets ([ ]).

# Arithmetic and Logic



- **Exponential function #i = EXP[#j];**

- When the result of the operation overflows, an alarm PS0119 is issued.
- A constant can be used instead of the #j variable.

- **ROUND function**

- When the ROUND function is included in an arithmetic or logic operation command, IF statement, or WHILE statement, the ROUND function rounds off at the first decimal place.

Example:

When #1=ROUND[#2]; is executed where #2 holds 1.2345, the value of variable #1 is 1.0.

- When the ROUND function is used in NC statement addresses, the ROUND function rounds off the specified value according to the least input increment of the address.

Example:

Creation of a drilling program that cuts according to the values of variables #1 and #2, then returns to the original position

Suppose that the increment system is 1/1000 mm, variable #1 holds 1.2345, and variable #2 holds 2.3456.

Then,

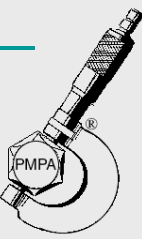
G00 G91 X-#1 ; Moves 1.235 mm in negative direction.

G01 X-#2 F300 ; Moves 2.346 mm in negative direction.

G00 X[#1+#2] ; Since  $1.2345 + 2.3456 = 3.5801$  in positive direction, the travel distance is 3.580, which does not return the tool to the original position.

This difference comes from whether addition is performed before or after rounding off.  
G00X-[ROUND[#1]+ROUND[#2]] ; must be specified to return the tool to the original position.

# Arithmetic and Logic



## - Rounding up and down to an integer (FUP and FIX)

With CNC, when the absolute value of the integer produced by an operation on a number is greater than the absolute value of the original number, such an operation is referred to as rounding up to an integer. Conversely, when the absolute value of the integer produced by an operation on a number is less than the absolute value of the original number, such an operation is referred to as rounding down to an integer. Be particularly careful when handling negative numbers.

Example:

Suppose that #1=1.2 and #2=-1.2.

When #3=FUP[#1] ; is executed, 2.0 is assigned to #3.

When #3=FIX[#1] ; is executed, 1.0 is assigned to #3.

When #3=FUP[#2] ; is executed, -2.0 is assigned to #3.

When #3=FIX[#2] ; is executed, -1.0 is assigned to #3.

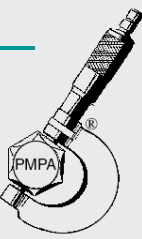


# Arithmetic and Logic



- Order of Operations
  - Algebraic order of operations
- P.E.M.D.A.S.
  1. Parenthesis - In macro programming [ ] = ( )
  2. Exponents
  3. Multiplication
  4. Division
  5. Addition
  6. Subtraction

# Arithmetic and Logic



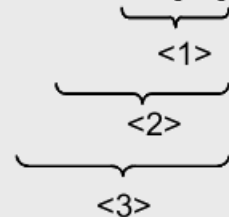
## - Priority of operations

<1> Functions

<2> Operations such as multiplication and division (\*, /, AND)

<3> Operations such as addition and subtraction (+, -, OR, XOR)

Example) #1=#2+#3\*SIN[#4];

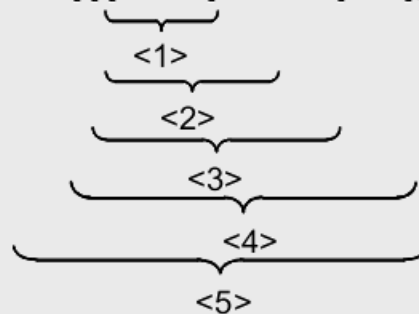


<1>, <2> and <3> indicate the order of operations.

## - Bracket nesting

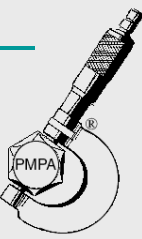
Brackets are used to change the order of operations. Brackets can be used to a depth of five levels including the brackets used to enclose a function. When a depth of five levels is exceeded, an alarm PS0118 occurs.

Example) #1=SIN [ [ [#2+#3] \*#4 +#5] \*#6];



<1> to <5> indicate the order of operations.

# Arithmetic and Logic



- **Brackets**

Brackets ([ ]) are used to enclose an expression.

Note that parentheses ( ) are used for comments.

- **Divisor**

When a divisor of zero is specified in a division, an alarm PS0112 occurs.

# Arithmetic and Logic



## ■ Precision and Errors

### - Range of variable values

Local and common variables can have a value in the following ranges. If the result of calculation exceeds the range, an alarm PS0111 is issued.

When bit 0 (F0C) of parameter No.6008 = 0

Maximum value: approx.  $\pm 10^{308}$

Minimum value: approx.  $\pm 10^{-308}$

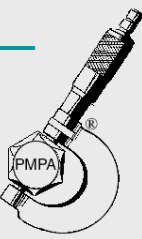
Numeric data handled by a custom macro conforms to the IEEE standard and is handled as a double-precision real number. An error resulting from operation depends on the precision.

When bit 0 (F0C) of parameter No.6008 = 1

Maximum value: approx.  $\pm 10^{47}$

Minimum value: approx.  $\pm 10^{-29}$

# Arithmetic and Logic



## Limitation

- **Caution concerning decreased precision**  
**When bit 0 (FOC) of parameter No. 6008 is set to 0**

- Addition and subtraction

Note that when an absolute value is subtracted from another absolute value in addition or subtraction, the relative error may become  $10^{-15}$  or greater.

For example, assume that #1 and #2 have the following true values in the process of operation.

(The following values are examples in the process of operation and cannot actually be specified from any program.)

#1=9876543210.987654321

#2=9876543210.987657777

You cannot obtain the following result with operation #2-#1:

#2-#1=0.000003456

This is because the precision of custom macro variables is 15 decimal digits. With this precision, the values of #1 and #2 become:

#1=9876543210.987650000

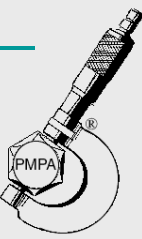
#2=9876543210.987660000

(Precisely, the actual values are slightly different from the above values because they are internally processed in binary.) Therefore, the result is:

#2-#1=0.000010000

A large error occurs.

# Arithmetic and Logic



## Limitation

- **Caution concerning decreased precision**  
When bit 0 (FOC) of parameter No. 6008 is set to 0

#1=9876543210.987654321

#2=9876543210.987657777

- Logical expressions  
Be aware of errors that can result from conditional expressions using EQ, NE, GT, LT, GE, and LE because they are processed basically in the same way as addition and subtraction. For example, if the following statement is used to decide whether #1 is equal to #2 in the above example, a correct decision may not be resulted because errors may occur:  
IF [#1 EQ #2]  
Evaluate the difference between #1 and #2 with:  
IF [ABS [#1-#2]LT 0.1]  
Then, assume that the values are equal when the difference does not exceed the allowable error range.

# Arithmetic and Logic



## Limitation

- **Caution concerning decreased precision**  
When bit 0 (FOC) of parameter No. 6008 is set to 0

- Trigonometric functions

The absolute error is guaranteed for trigonometric functions. However, the relative error is  $10^{-15}$  or greater. Carefully perform multiplication or division after executing a trigonometric function.

- FIX function

When using the FIX function for the result of an operation, be careful with the precision. For example, when the following operations are performed, the value of #3 may not always be 2.

```
N10 #1=0.002;  
N20 #2=#1*1000;  
N30 #3=FIX[#2];
```

This is because an error may occur in operation N20 and the result may not be

```
#2=2.0000000000000000
```

but a value a little smaller than 2 such as the following:

```
#2=1.9999999999999997
```

To prevent this, specify N30 as follows:

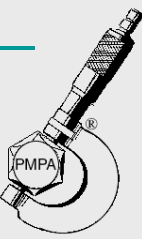
```
N30 #3=FIX[#2+0.001];
```

Generally, specify the FIX function as follows:

```
FIX[expression] → FIX[expression ±ε]
```

(Specify +ε when the value of the expression is positive or -ε when it is negative, and 0.1, 0.01, 0.001, ... for ε as required.)

# Arithmetic and Logic



**When bit 0 (F0C) of parameter No. 6008 is set to 1**  
 Errors may occur when operations are performed.

**Table 14.3 (b) Errors involved in operations**

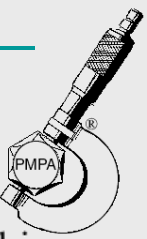
| Operation  | Average error          | Maximum error          | Type of error   |
|--|------------------------|------------------------|---|
| $a = b \cdot c$                                  | $1.55 \times 10^{-10}$ | $4.66 \times 10^{-10}$ | Relative error<br>$\left  \frac{\varepsilon}{a} \right $                            |
| $a = b / c$                                      | $4.66 \times 10^{-10}$ | $1.88 \times 10^{-9}$  |   |
| $a = \sqrt{b}$                                   | $1.24 \times 10^{-9}$  | $3.73 \times 10^{-9}$  |   |
| $a = b + c$<br>$a = b - c$                       | $2.33 \times 10^{-10}$ | $5.32 \times 10^{-10}$ | MIN $\left  \frac{\varepsilon}{b} \right $ , $\left  \frac{\varepsilon}{c} \right $ |
| $a = \text{SIN} [ b ]$<br>$a = \text{COS} [ b ]$ | $5.0 \times 10^{-9}$   | $1.0 \times 10^{-8}$   | Absolute error<br>$\left  \varepsilon \right $ degrees                              |
| $a = \text{ATAN} [ b ] / [ c ]$                  | $1.8 \times 10^{-6}$   | $3.6 \times 10^{-6}$   |   |

## NOTE

- 1 The relative error depends on the result of the operation.
- 2 Smaller of the two types of errors is used.
- 3 The absolute error is constant, regardless of the result of the operation.
- 4 Function TAN performs SIN/COS.
- 5 Note that, in the case of natural logarithm  $\#i = \text{LN}[\#j]$ ; and exponential function  $\#i = \text{EXP}[\#j]$ ; , the relative error may become  $10^{-8}$  or greater.
- 6 The operation result of exponential function  $\#i = \text{EXP}[\#j]$ ; overflows when  $\#j$  exceeds about 110.



# Arithmetic and Logic



- The precision of variable values is about 8 decimal digits. When very large numbers are handled in an addition or subtraction, the expected results may not be obtained.

Example:

When an attempt is made to assign the following values to variables #1 and #2:

#1=9876543210123.456

#2=9876543277777.777

the values of the variables become:

#1=9876543200000.000

#2=9876543300000.000

In this case, when #3=#2-#1; is calculated, #3=100000.000 results. (The actual result of this calculation is slightly different because it is performed in binary.)

- Also be aware of errors that can result from conditional expressions using EQ, NE, GE, GT, LE, and LT.

Example:

IF[#1 EQ #2] is effected by errors in both #1 and #2, possibly resulting in an incorrect decision.

Therefore, instead find the difference between the two variables with IF[ABS[#1-#2]LT0.001].

Then, assume that the values of the two variables are equal when the difference does not exceed an allowable limit (0.001 in this case).

- Also, be careful when rounding down a value.

Example:

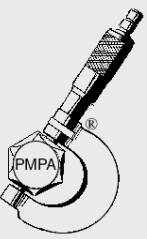
When #2=#1\*1000; is calculated where #1=0.002;, the resulting value of variable #2 is not exactly 2 but 1.99999997.

Here, when #3=FIX[#2]; is specified, the resulting value of variable #3 is not 2.0 but 1.0.

In this case, round down the value after correcting the error so that the result is greater than the expected number, or round it off as follows:

#3=FIX[#2+0.001]

#3=ROUND[#2]

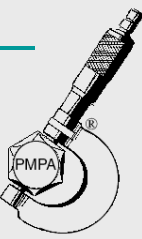


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# Questions Regarding Arithmetic and Logic?

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# Macro Statements and NC Statements



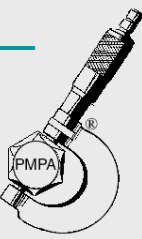
- The following blocks are referred to as macro statements:
  - Blocks containing arithmetic or logic operations
  - Blocks containing a control statement
    - GOTO, DO, END
  - Blocks containing a macro call command:
    - G65, G66, G67
    - Custom G and M codes that command a macro call
  
- Any block other than a macro statement is referred to as an NC statement

# Macro Statements and NC Statements



- Macro and NC Statement differences
  - When the machine is in single block mode, the machine does not stop when executing a macro
    - When parameter 6000 bit 5 (SBM) = 1 single block is effective in a macro
- Macro blocks are not regarded as blocks with no movement in cutter compensation mode (G41, G42)

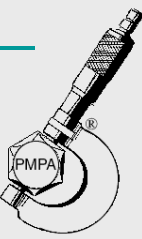
# Branch and Repetition Statements



- The flow of the program can be changed using branch and repetition statements.

|                       |   |       |                                       |
|-----------------------|---|-------|---------------------------------------|
| Branch and repetition | ┌ | GOTO  | (unconditional branch)                |
|                       | ├ | IF    | (conditional branch: if ..., then...) |
|                       | └ | WHILE | (repetition while ...)                |

# Unconditional Branch GOTO



- GOTO n causes an unconditional branch to sequence number n

Example:

GOTO 10; (causes the program to jump ahead or behind to sequence number N10)

## WARNING

Do not specify multiple blocks with the same sequence number in a single program. It is very dangerous to specify such blocks because the destination of a branch from the GOTO statement is undefined.

## NOTE

- 1 A backward branch takes more time as compared with a forward branch.
- 2 In the block with sequence number n, which is the branch destination of the GOTO n command, sequence number n must be located at the beginning of the block. Otherwise, the branch cannot be executed.

# GOTO Statement Using Stored Sequence Numbers



When the GOTO statement is executed in a custom macro control command, a sequence number search is made for sequence numbers stored at previous execution of the corresponding blocks at a high speed. Sequence numbers stored at previous execution indicate the sequence numbers for a subprogram call and the sequence numbers that are unique in the same program of the sequence numbers at previous execution, and the CNC records these sequence numbers.

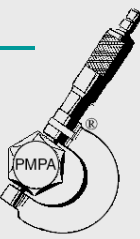
The storage type differs depending on the values of the following parameters.

- (1) When bit 1 (MGO) of parameter No. 6000 is set to 1
  - Fixed type: Up to 20 sequence numbers stored at execution of the corresponding blocks from the start of operation
- (2) When bit 4 (HGO) of parameter No. 6000 is set to 1
  - Variable type: Up to 30 sequence numbers stored at execution of the corresponding blocks before execution of the GOTO statement
  - History type: Up to 10 sequence numbers stored by a sequence number search previously made using the GOTO statement

The stored sequence numbers are canceled in the following cases:

- Immediately after power-on
- After a reset
- Operation after program registration or editing (including background editing and MDI program editing)

# GOTO Statement Using Stored Sequence Numbers



## **WARNING**

Do not specify multiple blocks with the same sequence number in a single program.

It is very dangerous to specify the sequence number of the branch destination before and after the GOTO statement and execute the GOTO statement because the branch destination changes according to the values of the parameters as shown below:

| When bit 1 (MGO) or 4 (HGO) of parameter No. 6000 is set to 1   | When both bits 1 (MGO) and 4 (HGO) of parameter No. 6000 are set to 0  |
|---|--|
| <pre>      :<br/>      N10;<br/>      :<br/>GOTO10;<br/>      :<br/>      N10;</pre> <p>A branch to N10 before the GOTO statement occurs.</p> | <pre>      :<br/>      N10;<br/>      :<br/>GOTO10;<br/>      :<br/>      N10;</pre> <p>A branch to N10 after the GOTO statement occurs.</p> |

When bit 1 (MGO) or 4 (HGO) of parameter No. 6000 is set to 1 and the GOTO statement is executed, the sequence number of the branch destination may not be contained in the sequence numbers stored at previous execution of the corresponding blocks. In this case, a branch to the sequence number in a block following the GOTO statement occurs (the destination is the same as when both bits are set to 0).

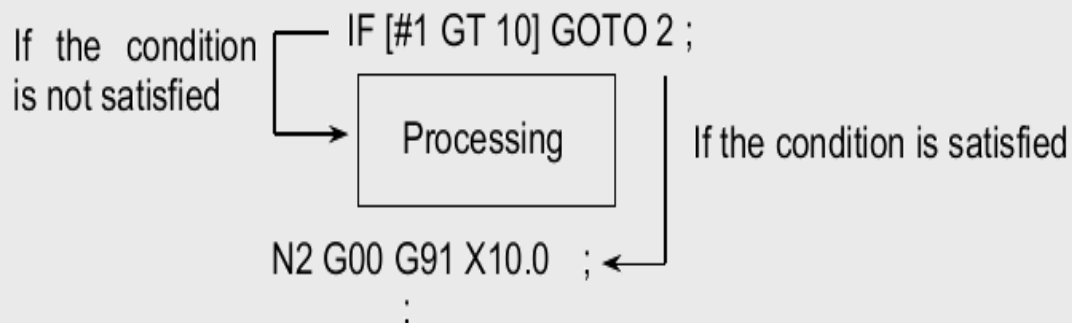


# Conditional Branch (IF Statement)

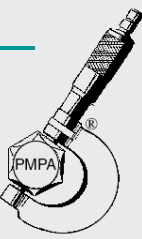


- IF[<conditional statement>] GOTO n
  - If the <conditional statement> is true then a branch to sequence number n occurs

If the value of variable #1 is greater than 10, a branch to sequence number N2 occurs.



# Conditional Branch (IF Statement)



- IF[<conditional statement>] THEN
  - If the conditional expression is satisfied (true), the macro statement after THEN will be executed.
  - Only a single macro statement can be executed

If the values of #1 and #2 are the same, 0 is assigned to #3.

```
IF[#1 EQ #2] THEN #3=0 ;
```

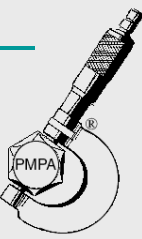
If the values of #1 and #2 are the same and those of #3 and #4 are also the same, 0 is assigned to #5.

```
IF[#1 EQ #2] AND [#3 EQ #4] THEN #5 = 0 ;
```

If the values of #1 and #2 are the same or those of #3 and #4 are the same, 0 is assigned to #5.

```
IF[#1 EQ #2] OR [#3 EQ #4] THEN #5 = 0 ;
```

# Conditional Branch (IF Statement)



## Explanation

### - <Conditional expression>

<Conditional expressions> are divided into <simple conditional expressions> and <complex conditional expressions>. In a <simple conditional expression>, a relational operator described in Table 14.5 (a) is specified between two variables or between a variable and constant to be compared. An <expression> can be used instead of a variable. With a <complex conditional expression>, an AND (logical AND), OR (logical OR), or XOR (exclusive OR) operation is performed for the results (true or false) of multiple <simple conditional expressions>.

### - Relational operators

Relational operators each consist of two letters and are used to compare two values to determine whether they are equal or one value is smaller or greater than the other value. Note that the equal sign (=) and inequality sign (>, <) cannot be used as a relational operator.

Table 14.5 (a) Relational operators

| Operator | Meaning                            |
|----------|------------------------------------|
| EQ       | Equal to(=)                        |
| NE       | Not equal to( $\neq$ )             |
| GT       | Greater than(>)                    |
| GE       | Greater than or equal to( $\geq$ ) |
| LT       | Less than(<)                       |
| LE       | Less than or equal to( $\leq$ )    |

# Sample Program

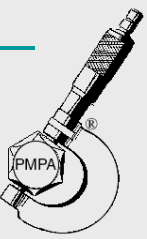


The sample program below finds the total of numbers 1 to 10.

```
O9500 ;  
  #1=0 ; ..... Initial value of the variable to hold the sum  
  #2=1 ; ..... Initial value of the variable as an addend  
N1 IF[#2 GT 10] GOTO 2 ; Branch to N2 when the addend is greater than 10  
  #1=#1+#2 ; ..... Calculation to find the sum  
  #2=#2+1 ; ..... Next addend  
  GOTO 1 ; ..... Branch to N1  
N2 M30 ; ..... End of program
```

$$\#1 = 1+2+3+4+5+6+7+8+9+10$$

# Macro Examples: (Tool Life Management)



This example counts tool use frequency and stops the machine once the tool life is expired.

Variables:

#505=Tool Life for 1<sup>st</sup> Tool

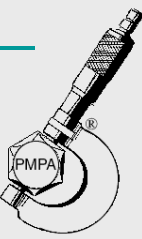
#506=1<sup>st</sup> Tool Life Counter

#507=Tool Life for 2<sup>nd</sup> Tool

#508=2<sup>nd</sup> Tool Life Counter

When a tool has reached its life expectancy the counter is set back to zero and an alarm message is generated to inform the operator which tool to change.

# Macro Examples: (Tool Life Management)



O1204(PROGRAM)  
(VARIABLES TO SET BY OPERATOR)  
(#505= 1ST TOOL LIFE AMOUNT)  
(#507= 2ND TOOL LIFE AMOUNT)

(CHECK TOOL LIFE)  
IF[#506GE#505]GOTO881  
IF[#508GE#507]GOTO882

G00G40G18G99G20G97

T1515(1ST TOOL)  
G0G99X.550Z.05M3S3000  
G1G42X.520Z.015F.005  
G1X.490Z0F.001  
G1X-.015  
G0Z-.05  
G28U0  
#506=[#506+1](ADD COUNT)

T1616 (2ND TOOL)  
G0G99X0Z-.05M3S3000  
G1Z.1F.002  
G0Z-.05T0  
G28U0  
#508=[#508+1](ADD COUNT)

(RESET COUNT AND ALARMS)  
GOTO999(NO TOOLS EXPIRED)

N881(1<sup>ST</sup> TOOL ALARM)  
#506=0  
#3000=1(T1515 IS EXPIRED)

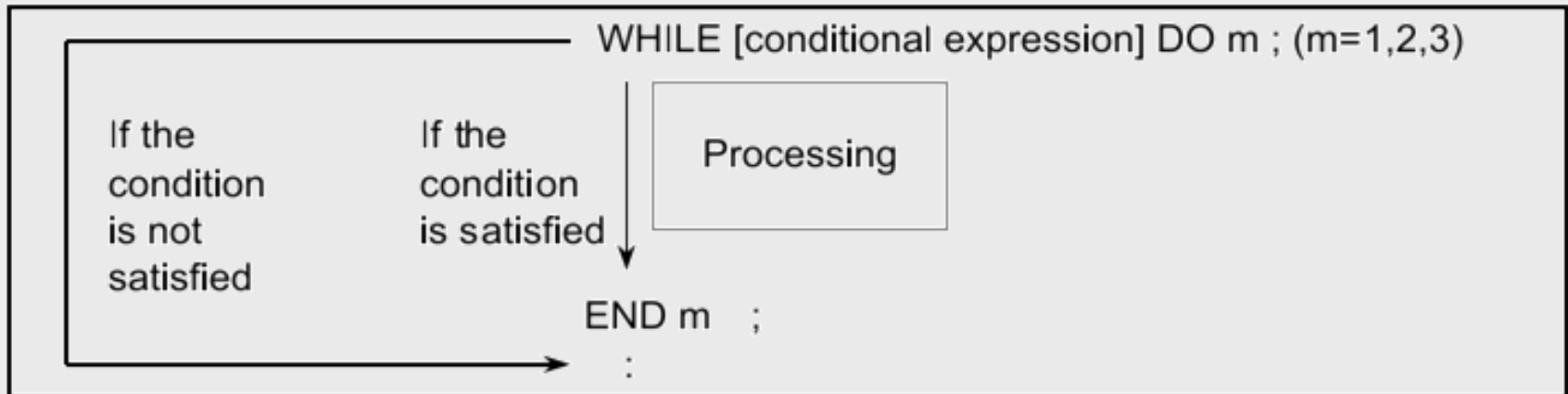
N882(2ND TOOL ALARM)  
#508=0  
#3000=2(T1616 IS EXPIRED)

N999  
M30

# Repetition (WHILE Statement)

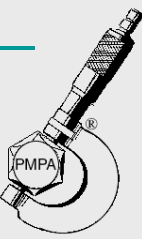


- A conditional statement is specified after WHILE. As long as the conditional statement is satisfied (true) the program from DO to END is executed.



While the specified condition is satisfied, the program from DO to END after WHILE is executed. If the specified condition is not satisfied, program execution proceeds to the block after END. The same format as for the IF statement applies. A number after DO and a number after END are identification numbers for specifying the range of execution. The numbers 1, 2, and 3 can be used. When a number other than 1, 2, and 3 is used, an alarm PS0126 occurs.

# Repetition (WHILE Statement)



The sample program below finds the total of numbers 1 to 10.

```
O9500 ;  
  #1=0 ; ..... Initial value of the variable to hold the sum  
  #2=1 ; ..... Initial value of the variable as an addend  
N1 IF[#2 GT 10] GOTO 2 ; Branch to N2 when the addend is greater than 10  
  #1=#1+#2 ; ..... Calculation to find the sum  
  #2=#2+1 ; ..... Next addend  
  GOTO 1 ; ..... Branch to N1  
N2 M30 ; ..... End of program
```

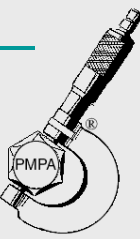
Takes longer to search backward

Example using WHILE\_DO to do the same thing:

```
O0001;  
#1=0;  
#2=1;  
WHILE[#2 LE 10] DO 1; ← Processes faster  
#1=#1+#2;  
#2=#2+1;  
END 1;  
M30;
```



# Repetition (WHILE Statement)



## ■ Nesting

- The identification numbers (1 to 3) in a DO\_END loop can be used as many times in a program as desired (reuse).
- When a program contains overlapping DO ranges alarm PS0124 is generated.

1. The identification numbers (1 to 3) can be used as many times as required.

```
WHILE [ ... ] DO 1 ;  
    Processing  
END 1 ;  
:  
WHILE [ ... ] DO 1 ;  
    Processing  
END 1 ;  
:
```

2. DO ranges cannot overlap.

```
WHILE [ ... ] DO 1 ;  
    Processing  
WHILE [ ... ] DO 2 ;  
    Processing  
END 2 ;  
END 1 ;
```

3. DO loops can be nested to a maximum depth of three levels.

```
WHILE [ ... ] DO 1 ;  
    :  
    WHILE [ ... ] DO 2 ;  
        :  
        WHILE [ ... ] DO 3 ;  
            Processing  
        END 3 ;  
    END 2 ;  
    :  
END 1 ;
```

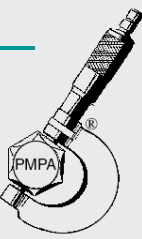
4. Control can be transferred to the outside of a loop.

```
WHILE [ ... ] DO 1 ;  
    IF [ ... ] GOTO n ;  
END 1 ;  
Nn
```

5. Branches cannot be made to a location within a loop.

```
IF [ ... ] GOTO n ;  
    :  
    WHILE [ ... ] DO 1 ;  
        :  
        Nn ... ;  
    END 1 ;
```

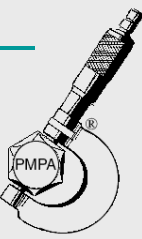
# Repetition (WHILE Statement)



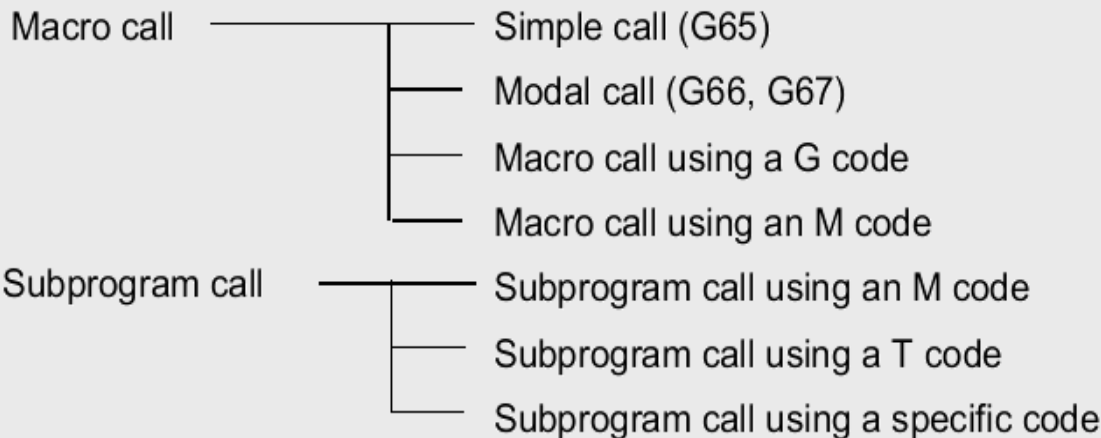
## ■ Limitations

- ❑ Infinite loops – When DO m is specified without a WHILE statement preceding, an infinite loop is created between the DO and END commands.
- ❑ Processing time – When a branch to the sequence number specified in a GOTO statement occurs, the sequence number is searched for. In the case of processing in the reverse direction use a While statement to reduce processing time.
- ❑ Null variable – In conditional expressions that use EQ and NE, a null variable is not treated the same as 0. In all other conditional expressions null = 0

# Macro Call



- A macro program can be called using any of the following methods.
- There are two types of calling methods: macro call and subprogram call



# Macro Call



## Limitation

### - Call nesting

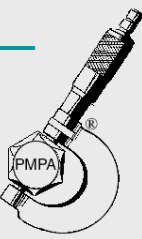
Macro calls can be nested to a depth of up to five levels and subprogram calls can be nested to a depth of up to ten levels; calls can be nested to a depth of up to 15 levels in total.

### - Differences between macro calls and subprogram calls

Macro call (G65, G66, Ggg, or Mmm) differs from subprogram call (M98, Mmm, or Ttt) as described below.

- With a macro call, an argument (data passed to a macro) can be specified. A subprogram call does not have this capability.
- If a macro call block contains another NC command (such as G01 X100.0 G65 Pp), an alarm PS0127 occurs.
- If a subprogram call block contains another NC command (such as G01 X100.0 M98 Pp), the subprogram is called after the command is executed.
- In any macro call block, the machine does not stop in the single block mode.  
If a subprogram call block contains another NC command (such as G01 X100.0 M98 Pp), the machine stops in the single block mode.
- With a macro call, the level of local variables changes. With a subprogram call, the level of local variables does not change. (See "Local variable levels" in Limitation of Subsection 14.6.1.)

# Simple Macro Call (G65)



- When G65 is specified, the custom macro sub program at address P is called. Data (arguments) can be passed to the macro program.

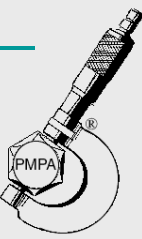
```
G65 P p L ℓ <argument-  
specification> ;
```

P : Number of the program to call  
ℓ : Repetition count (1 by default)  
Argument : Data passed to the macro

```
O0001 ;  
:  
G65 P9010 L2 A1.0 B2.0 ;  
:  
M30 ;
```

```
O9010 ;  
#3=#1+#2 ;  
IF [#3 GT 360] GOTO 9 ;  
G00 G91 X#3 ;  
N9 M99 ;
```

# Simple Macro Call (G65)



G65 P p L ℓ <argument-specification> ;

P : Number of the program to call

ℓ : Repetition count (1 by default)

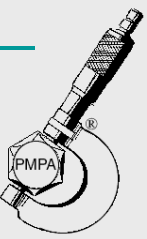
Argument : Data passed to the macro

```
O0001 ;
:
G65 P9010 L2 A1.0 B2.0 ;
:
M30 ;
```

```
O9010 ;
#3=#1+#2 ;
IF [#3 GT 360] GOTO 9 ;
G00 G91 X#3 ;
N9 M99 ;
```

- After G65, address P is the program number of the macro program.
- When a number of repetitions are required, specify the number after address L. Range is 1-999999999. When L is omitted the value of L is assumed to be 1.
- By specifying arguments (A n, B n, Cn) values are passed to the corresponding variable.

# Argument Specification I



Two types of argument specification are available. Argument specification I uses letters other than G, L, O, N, and P once each. Argument specification II uses A, B, and C once each and also uses I, J, and K up to ten times. The type of argument specification is determined automatically according to the letters used.

- Argument specification I

| Address | Variable number |
|---------|-----------------|
| A       | #1              |
| B       | #2              |
| C       | #3              |
| D       | #7              |
| E       | #8              |
| F       | #9              |
| H       | #11             |

| Address | Variable number |
|---------|-----------------|
| I       | #4              |
| J       | #5              |
| K       | #6              |
| M       | #13             |
| Q       | #17             |
| R       | #18             |
| S       | #19             |

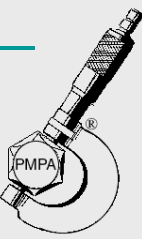
| Address | Variable number |
|---------|-----------------|
| T       | #20             |
| U       | #21             |
| V       | #22             |
| W       | #23             |
| X       | #24             |
| Y       | #25             |
| Z       | #26             |

- Addresses G, L, N, O, and P cannot be used in arguments.
- Addresses that need not be specified can be omitted. Local variables corresponding to an omitted address are set to null.
- Addresses do not need to be specified alphabetically. They conform to word address format. I, J, and K need to be specified alphabetically, however.  
Argument specification I is always used for I, J, and K by setting bit 7 (IJK) of parameter No. 6008 to 1

## Example

- When bit 7 (IJK) of parameter No. 6008 is 0, I\_ J\_ K\_ means that I = #4, J = #5, and K = #6 while K\_ J\_ I\_ means K = #6, J = #8, and I = #10 because argument specification II is used.
- When bit 7 (IJK) of parameter No. 6008 is 1, K\_ J\_ I\_ means that I = #4, J = #5, and K = #6, which is the same as with I\_ J\_ K\_, because argument specification I is used.

# Argument Specification II



Argument specification II uses A, B, and C once each and uses I, J, and K up to ten times. Argument specification II is used to pass values such as three-dimensional coordinates as arguments.

| Address        | Variable number |
|----------------|-----------------|
| A              | #1              |
| B              | #2              |
| C              | #3              |
| I <sub>1</sub> | #4              |
| J <sub>1</sub> | #5              |
| K <sub>1</sub> | #6              |
| I <sub>2</sub> | #7              |
| J <sub>2</sub> | #8              |
| K <sub>2</sub> | #9              |
| I <sub>3</sub> | #10             |
| J <sub>3</sub> | #11             |

| Address         | Variable number |
|-----------------|-----------------|
| IK <sub>3</sub> | #12             |
| I <sub>4</sub>  | #13             |
| J <sub>4</sub>  | #14             |
| K <sub>4</sub>  | #15             |
| I <sub>5</sub>  | #16             |
| J <sub>5</sub>  | #17             |
| K <sub>5</sub>  | #18             |
| I <sub>6</sub>  | #19             |
| J <sub>6</sub>  | #20             |
| K <sub>6</sub>  | #21             |
| I <sub>7</sub>  | #22             |

| Address         | Variable number |
|-----------------|-----------------|
| J <sub>7</sub>  | #23             |
| K <sub>7</sub>  | #24             |
| I <sub>8</sub>  | #25             |
| J <sub>8</sub>  | #26             |
| K <sub>8</sub>  | #27             |
| I <sub>9</sub>  | #28             |
| J <sub>9</sub>  | #29             |
| K <sub>9</sub>  | #30             |
| I <sub>10</sub> | #31             |
| J <sub>10</sub> | #32             |
| K <sub>10</sub> | #33             |

- Subscripts of I, J, and K for indicating the order of argument specification are not written in the actual program.

## NOTE

When bit 7 (IJK) of parameter No. 6008 is 1, argument specification II cannot be used.



# Simple Macro Call (G65)



## Limitation

### - Format

G65 must be specified before any argument.

### - Mixture of argument specifications I and II

The CNC internally identifies argument specification I and argument specification II. If a mixture of argument specification I and argument specification II is specified, the type of argument specification specified later takes precedence.

[Example]

```
G65 A1.0 B2.0 I-3.0 I4.0 D5.0 P1000 ;
```

(Variables)

#1:1.0 ←

#2:2.0 ←

#3:

#4:-3.0 ←

#5:

#6:

#7:4.0 ←

5.0 ←

When both the I4.0 and D5.0 arguments are commanded for variable #7 in this example, the latter, D5.0, is valid.

### - Position of the decimal point

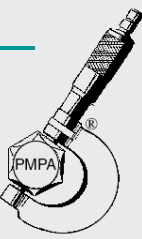
The units used for argument data passed without a decimal point correspond to the least input increment of each address.



## CAUTION

The value of an argument passed without a decimal point may vary according to the system configuration of the machine. It is good practice to use decimal points in macro call arguments to maintain program compatibility.

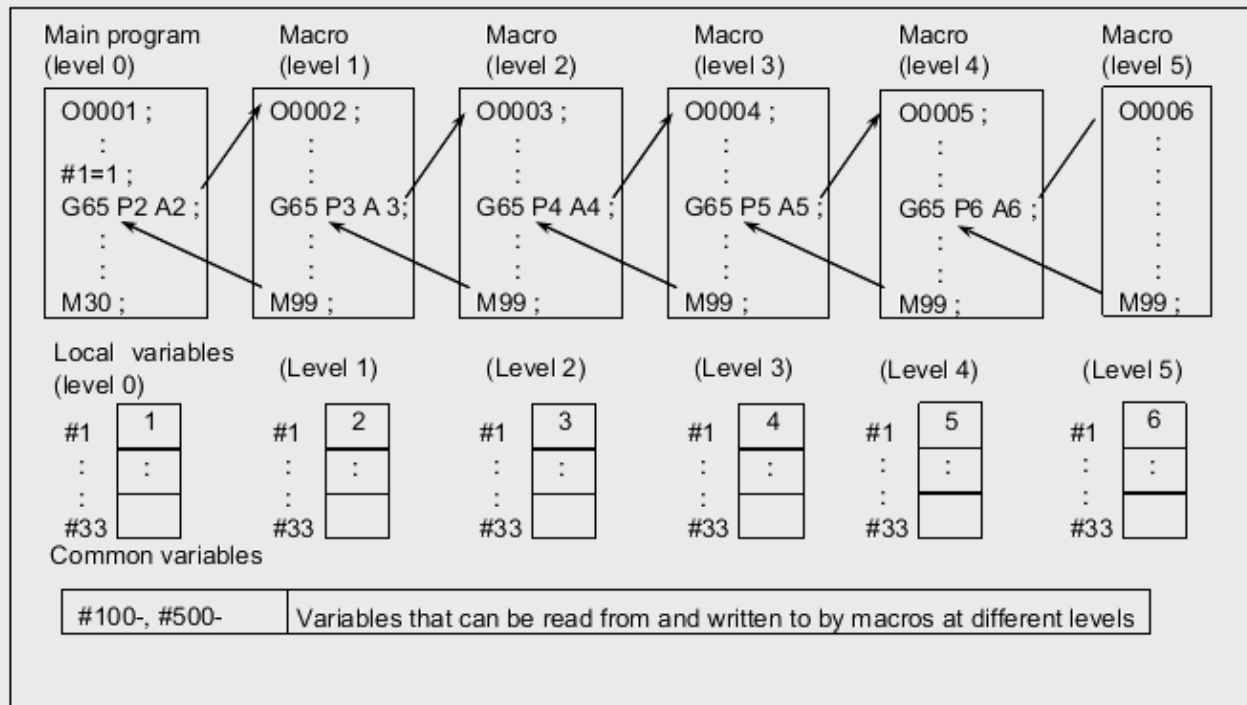
# Macro Call Nesting



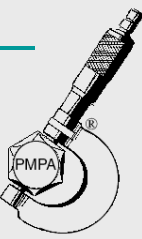
Macro calls can be nested to a depth of up to five levels including simple calls (G65) and modal calls (G66). Subprogram calls can be nested to a depth of up to 15 levels including macro calls. A macro program can also be called during MDI operation in the same way.

## - Local variable levels

- Local variables from level 0 to 5 are provided for nesting.
- The level of the main program is 0.
- Each time a macro is called (with G65, G66, Ggg, or Mmm), the local variable level is incremented by one. The values of the local variables at the previous level are saved in the CNC.
- When M99 is executed in a macro program, control returns to the calling program. At that time, the local variable level is decremented by one; the values of the local variables saved when the macro was called are restored.



# Macro Examples: Macro G & M Code Sub Program Calls

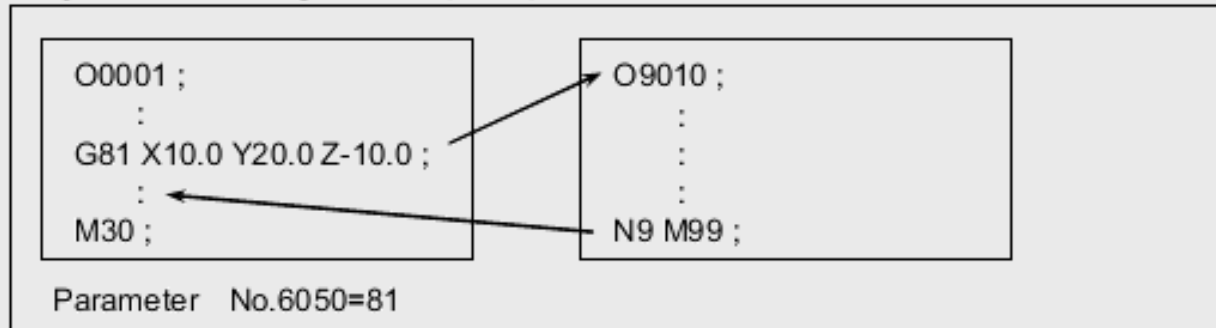


- Macro sub-programs can also be called with G and M codes by setting parameters.
- Any value can be set to these parameters as long as it is not an existing G or M code.
- Parameters 6050-6059 correspond with program numbers 9010-9019 for macro call by G-code.
- Parameters 6080-6089 correspond with program numbers 9020-9029 for macro call by M-code.

# Using a G-Code



By setting a G code number used to call a macro program in a parameter, the macro program can be called in the same way as for a simple call (G65).



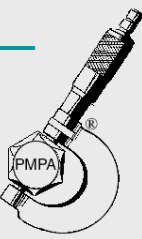
## Explanation

By setting a G code number from -9999 to 9999 used to call a custom macro program (O9010 to O9019) in the corresponding parameter (No.6050 to No.6059), the macro program can be called in the same way as with G65.

If a negative G code is set, a modal call (equivalent to G66) is made.

For example, when a parameter is set so that macro program O9010 can be called with G81, a user-specific cycle created using a custom macro can be called without modifying the machining program.

# Using a G-Code



## - Correspondence between parameter numbers and program numbers

| Parameter number | Program number |
|------------------|----------------|
| 6050             | O9010          |
| 6051             | O9011          |
| 6052             | O9012          |
| 6053             | O9013          |
| 6054             | O9014          |
| 6055             | O9015          |
| 6056             | O9016          |
| 6057             | O9017          |
| 6058             | O9018          |
| 6059             | O9019          |

## - Repetition

As with a simple call, a number of repetitions from 1 to 99999999 can be specified at address L.

## - Argument specification

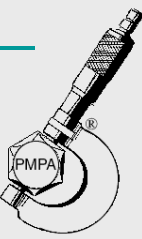
As with a simple call, two types of argument specification are available: Argument specification I and argument specification II. The type of argument specification is determined automatically according to the addresses used.

## Limitation

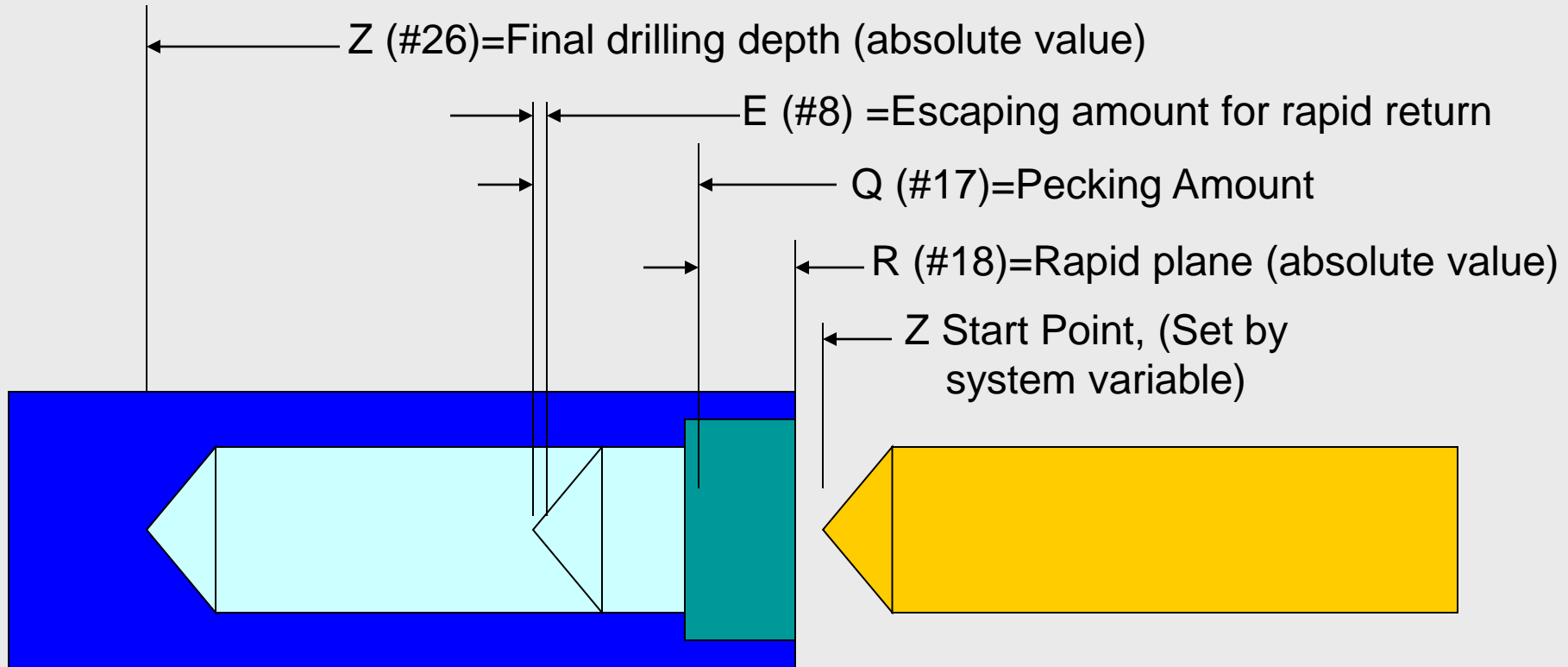
### - Nesting of calls using G codes

- To call another program in a program called using a G code, only G65, M98, or G66 can be used normally.
- When bit 6 (GMP) of parameter No. 6008 is set to 1, a call using an M code, T code, or specific code can be performed in a program called using a G code.

# Macro Examples: Custom G-Code Macro



- Start with a desired application and decide how much control you need.
- List out your arguments.
- Document it carefully once it is proven.
- Name it: Set parameter 6058=383, G383 now calls program O9018.



# Macro Examples: Custom G-Code Macro



- Parameter Screen set for G383 Macro:

PARAMETER 00000 N00000

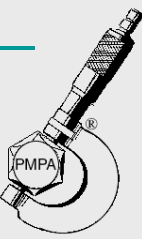
|       |                      |       |                       |
|-------|----------------------|-------|-----------------------|
| 06043 | MCR DPG NUM          | 06052 | 0                     |
|       | <input type="text"/> | 06053 | 0                     |
| 06044 | SUB TOP M            | 06054 | 0                     |
|       | <input type="text"/> | 06055 | 0                     |
| 06045 | SUB TOP O            | 06056 | 0                     |
|       | <input type="text"/> | 06057 | 0                     |
| 06046 | SUB M NUM            | 06058 | 383                   |
|       | <input type="text"/> | 06059 | 0                     |
| 06047 | MACRO TOP M          | 06060 | MACRO CALL DPG (9840) |
|       | <input type="text"/> |       | 0                     |
| 06048 | MACRO TOP O          | 06061 | MACRO CALL DPG (9841) |
|       | <input type="text"/> |       | 0                     |
| 06049 | MACRO M NUM          | 06062 | MACRO CALL DPG (9842) |
|       | <input type="text"/> |       | 0                     |
| 06050 | MACRO CALL G         | 06063 | MACRO CALL DPG (9843) |
|       | <input type="text"/> |       | 0                     |
| 06051 | <input type="text"/> |       | 0                     |

A>>

MDI \*\*\*\* \* \* \* \* 04:05:22 NC2

|   |         |       |        |        |       |         |          |   |
|---|---------|-------|--------|--------|-------|---------|----------|---|
| < | NO. SRH | ON: 1 | OFF: 0 | +INPUT | INPUT | F INPUT | F OUTPUT | + |
|---|---------|-------|--------|--------|-------|---------|----------|---|

# Macro Examples: Custom G-Code Macro



## Macro Arguments:

R (#18)= Rapid plane start point. Absolute Z value

Z (#26)= Final drill depth.

Q (#17)= 1<sup>st</sup> drilling peck depth

E (#8)= Escaping amount for pecking return

T (#20)= Dwell time at last peck

F (#9)= Drilling feed rate

A (#1)= Peck reduction percentage

B (#2)= Minimum pecking amount

## Program notes:

\*Z axis returns to start point after each peck.

\*The R rapid plane is an absolute Z-location.

\*A= peck reduction by percentage. Example .2= 20% peck reduction each time.

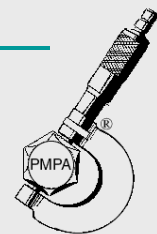
\*B= Minimum pecking amount allowed.

\*If A and B are omitted the pecking amount is the “Q” value throughout the cycle.

\*Select G98 or G99 mode prior to G383.



# Macro Examples: Custom G-Code Macro



%

O9018(G383 PECK DRILL CYCLE)

(BEGINNING CALCULATIONS)

#110=#5002(SET START Z)

#112=[1.0-#1](PECK MULTIPLIER)

#113=#17(SET 1ST PECK)

(DECIDE Z- OR Z+)

IF[#5002GT#26]GOTO200(Z- DIRECTION)

(\*\*\*\*\*)

(Z+ DIRECTION)

#111=[#18+#8](SET DRILL START)

IF[#17EQ0]GOTO100(NO PECKING)

(WHOLE PECKS)

WHILE[[#111+#113]LT#26]DO1

G0Z[#111-#8](RAPID IN)

G1Z[#111+#113]F#9(DRILLING PECK)

#111=#5002(READ DRILL END Z)

G0Z#110(GO BACK TO START POS.)

#113=[#113\*#112](REDUCE PECK)

IF[#113LT#2]THEN#113=#2(PECK CLAMP)

END1

N100(FINAL DEPTH)

G0Z[#111-#8]

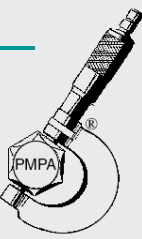
G1Z#26F#9

G4U#20

G0Z#110

GOTO300(GO TO END)

# Macro Examples: Custom G-Code Macro



```
N200(Z- DIRECTION)
#111=[#18-#8](SET DRILL START)

IF[#17EQ0]GOTO201(NO PECKING)

(WHOLE PECKS)
WHILE[[#111-#113]GT#26]DO1
  G0Z[#111+#8](RAPID IN)
  G1Z[#111-#113]F#9(DRILLING PECK)
  #111=#5002(READ DRILL END Z)
  G0Z#110(GO BACK TO START POS.)

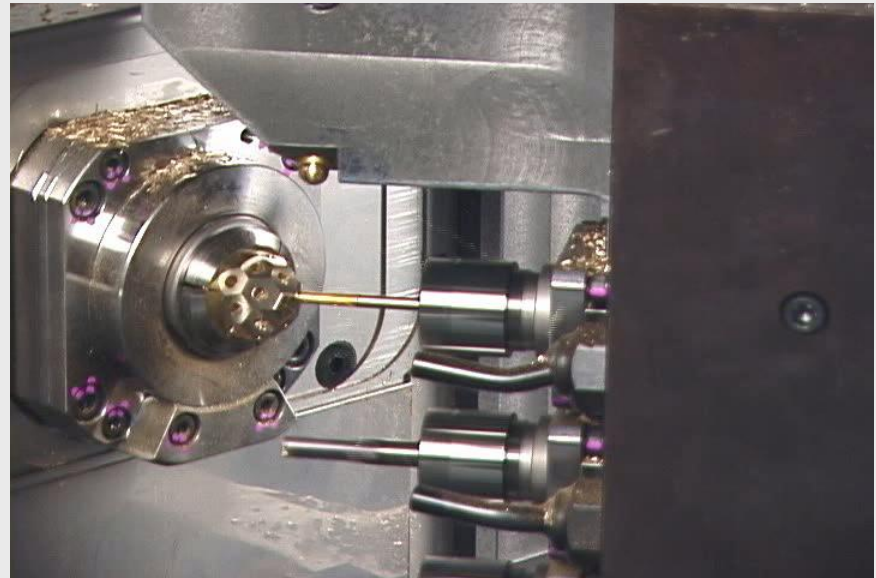
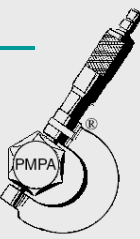
#113=[#113*#112](REDUCE PECK)

IF[#113LT#2]THEN#113=#2(PECK CLAMP)
  END1
```

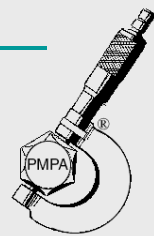
```
N201(FINAL DEPTH)
G0Z[#111+#8]
G1Z#26F#9
G4U#20
G0Z#110

N300(END)
M99
%
```

# Example Custom Angle Drilling Cycle For a Live Tool Lathe

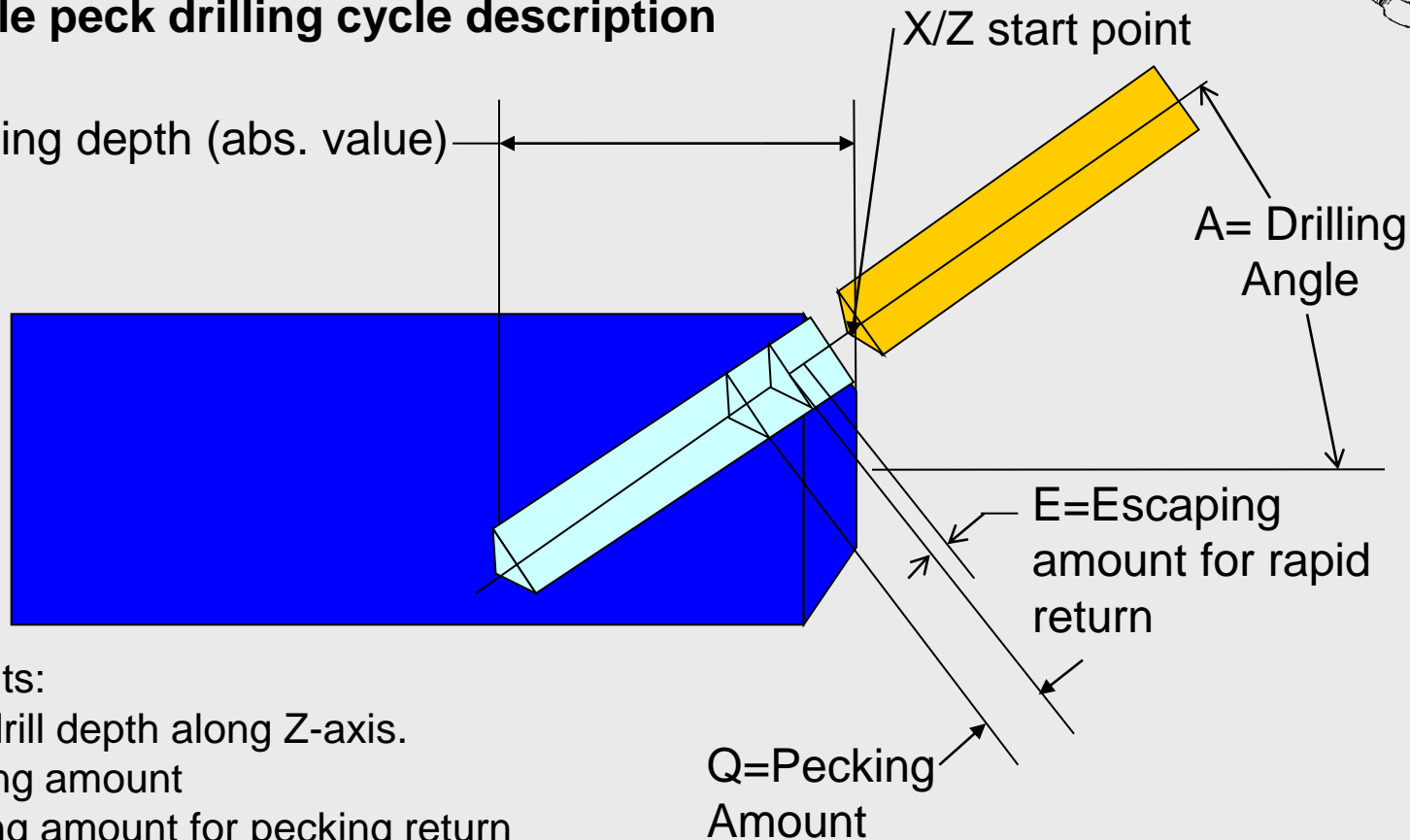


# Macro Examples: Custom G-Code Macro



## G183 angle peck drilling cycle description

Z=Final drilling depth (abs. value)



### Macro Arguments:

Z (#26)= Final drill depth along Z-axis.

Q (#17)= Pecking amount

E (#8)= Escaping amount for pecking return

T (#20)= Dwell time at last peck

F (#9)= Drilling feed rate

A (#1)= Angle for drilling

R (#18)= Retract feed rate

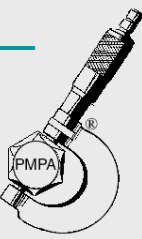
### Program notes:

\*X and Z axes return to start point after each peck.

\*If "Q" value is set to 0 then no pecking is done.

# Macro Examples: Custom G-Code Macro

## G183 angle peck drilling cycle description



```
%
O9019(G183 ANGLED PECKING)
(Z+ DIRECTION DRILLING)
(SET PARAMETER 6059=183)
(G283A,Z,Q,E,F,R,T)
(Z#26=ZENDPOINT FOR DRILLING)
(A#1=ANGLE FOR DRILLING)
(Q#17=PECK AMOUNT)
(E#8=ESCAPING AMOUNT)
(F#9=CUTTING FEED RATE)
(T#20=LAST PECK DWELL)
(R#18=RETRACT FEEDRATE)
(IF Q=0 THEN NO PECKING)

#108=#5004(START Y)
#109=#5002(START Z)
#110=#5004(Y ESCAPE)
#111=#5002(Z ESCAPE)
#112=#5004(Y DRILL END)
#113=#5002(Z DRILL END)

#115=[#26-#5002](Z-LEG)
#116=[#115/COS[#1]](HYP. DISTANCE)

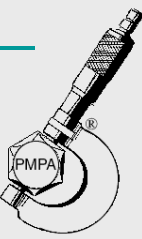
IF[#17EQ0]GOTO300(NO PECKING)

#117=[FIX[#116/#17]](WHOLE PECKS)
#107=0(COUNTER)
```

```
(WHOLE PECKS)
WHILE[#117GT#107]DO1
G98G1Y#110Z#111F#18(GO TO ESCAPING POS.)
G1Y#112Z#113F#9(FEED TO END)
G1V-[[#17]*SIN[#1]]W[[#17]*COS[#1]]F#9(DRILLING PECK)
#112=#5004(READ DRILL END Y)
#113=#5002(READ DRILL END Z)
G1V[#8*SIN[#1]]W-[#8*COS[#1]]F#9(ESCAPING AMOUNT)
#110=#5004(READ ESCAPE Y)
#111=#5002(READ ESCAPE Z)
G1Y#108Z#109F#18(GO BACK TO START POS.)
#107=[#107+1](ADD COUNT)
END1

N300(FINAL DEPTH)
G98G1Y#110Z#111F#18
G1Y#112Z#113F#9(FEED TO END)
G1V-[[#26-#113]*TAN[#1]]Z#26F#9
G4U#20
G1Y#108Z#109F#18
M99
%
```

# Macro Call Using an M-Code



By setting an M code number used to call a macro program in a parameter, the macro program can be called in the same way as with a simple call (G65).



## Explanation

By setting an M code number from 3 to 99999999 used to call custom macro program O9020 to O9029 in the corresponding parameter (Nos. 6080 to 6089), the macro program can be called in the same way as with G65.

# Macro Call Using an M-Code



## - Correspondence between parameter numbers and program numbers

| Parameter number | Corresponding program number |
|------------------|------------------------------|
| 6080             | O9020                        |
| 6081             | O9021                        |
| 6082             | O9022                        |
| 6083             | O9023                        |
| 6084             | O9024                        |
| 6085             | O9025                        |
| 6086             | O9026                        |
| 6087             | O9027                        |
| 6088             | O9028                        |
| 6089             | O9029                        |

Example)

When parameter No. 6080 is set to 990, O9020 is called using M990.

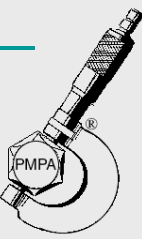
## - Repetition

As with a simple call, a number of repetitions from 1 to 99999999 can be specified at address L.

## - Argument specification

As with a simple call, two types of argument specification are available: Argument specification I and argument specification II. The type of argument specification is determined automatically according to the addresses used.

# Macro Examples: Custom M-Code Macro



Automatic cut-off macro;

Set parameter 6080 to 910. M910 call program O9020.

Notes: Cutoff location and offset must match

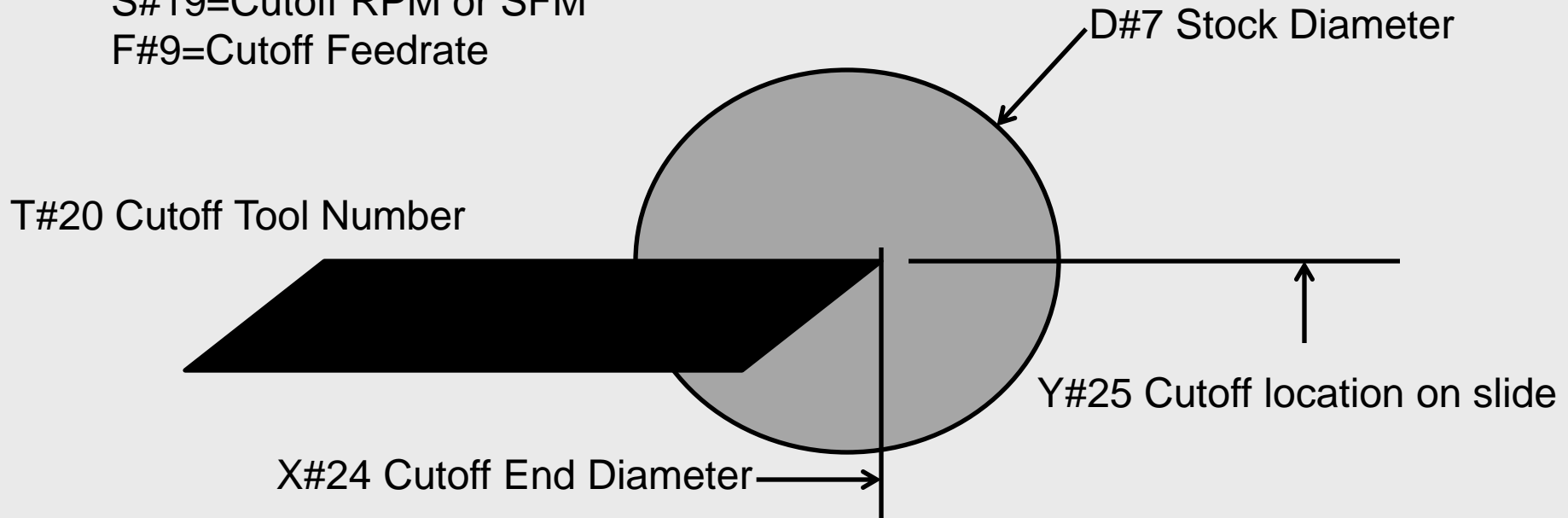
Example T7=T0707

C#3=G96 or G97 mode

I#4=G68 or G69 status

S#19=Cutoff RPM or SFM

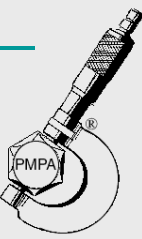
F#9=Cutoff Feedrate





# Macro Examples: Custom M-Code Macro

## Automatic Cutoff Macro



M-Code call: M910 I69 T7 D1.0 X-.04 C96 S400 F.002

O9020(AUTO CUT-OFF)

G50S3000(SPINDLE SPEED LIMIT)

(ROUTINE START)

G#4(G68 OR G69)

T#20(OFFSET CALL)

(CHECK X-AXIS ABS. POSITION)

IF[#5001GT0]GOTO10

(CHECK Y-AXIS MACH. POSITION)

IF[#5024LT[#25-.02]]GOTO10

IF[#5024GT[#25+.02]]GOTO10

M99

N10(CUTOFF)

#3006=1(CHECK BEFORE CUTOFF)

M8

G28U0

M10

M60

T[[#20\*100]+#20]

G#3M3S#19

G0X[#7+.05]

G99G1X#24F#9

M9

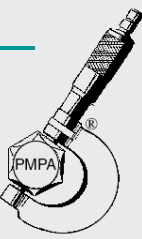
M5

#3006=1(CUTOFF FINISH)

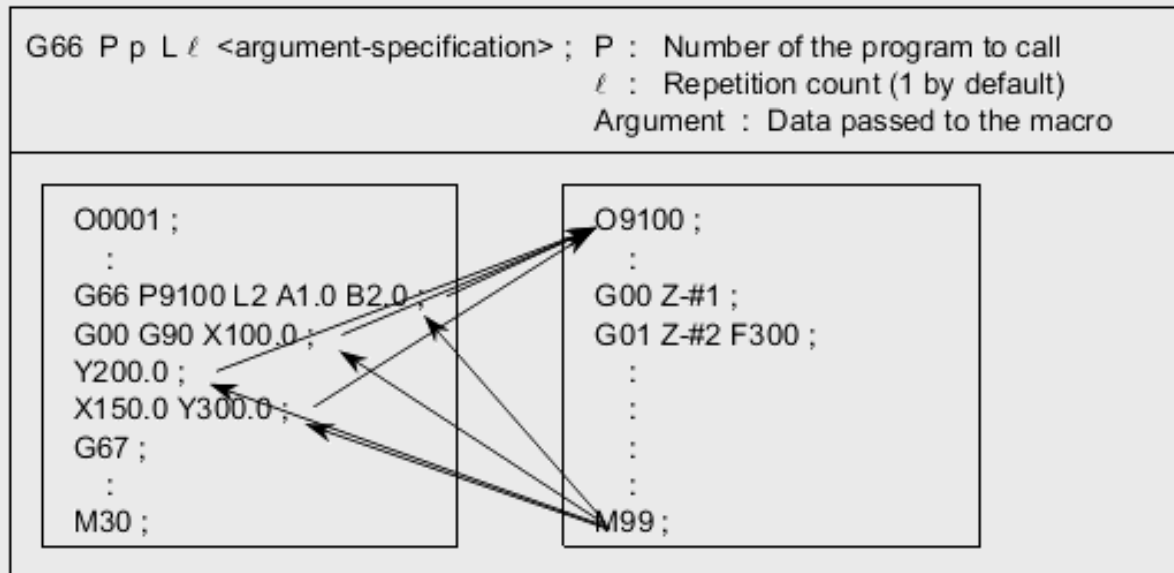
M99

%

# Modal Macro Call



Once G66 is issued to specify a modal call a macro is called after a block specifying movement along axes is executed. This continues until G67 is issued to cancel a modal call.



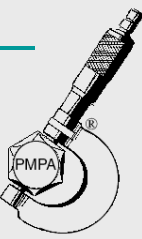
## - Call

- After G66, specify at address P a program number subject to a modal call.
- When a number of repetitions is required, a number from 1 to 999999999 can be specified at address L.
- As with a simple call (G65), data passed to a macro program is specified in arguments.
- In the G66 mode, a macro can be called.

## - Cancellation

When a G67 code is specified, modal macro calls are no longer performed in subsequent blocks.

# Modal Macro Call



## - Call nesting

Macro calls can be nested to a depth of up to five levels including simple calls (G65) and modal calls (G66). Subprogram calls can be nested to a depth of up to 15 levels including macro calls.

## - Modal call nesting

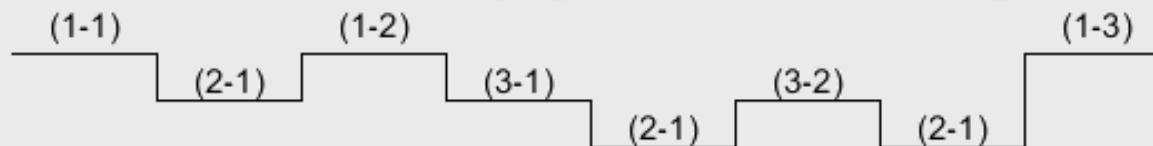
For a single modal call (when G66 is specified only once), each time the move command is executed, the specified macro is called. When nested modal macro calls are specified, the macro at the next higher level is called each time the move command for a macro call is executed.

Macros are called in reverse order in which they are specified. Each time G67 is issued, the macros are canceled one by one in reverse order in which they are specified.

[Example]

```
G66 P9100 ;           O9100 ;           O9200 ;
X10.0 ;   (1-1)       Z50.0 ;   (2-1)     X60.0 ;   (3-1)
G66 P9200 ;           M99 ;             Y70.0 ;   (3-2)
X15.0 ;   (1-2)       M99;
G67 ;           Cancels P9200.
G67 ;           Cancels P9100.
X-25.0 ;   (1-3)
```

Execution order of the above program (blocks not containing the move command omitted)



\* No modal call is performed after (1-3) because the mode is not the macro call mode.

# Modal Macro Call



## Limitation

- G66 and G67 blocks are specified in pairs in the same program. If a G67 code is specified not in the G66 mode, an alarm PS1100 occurs. Bit 0 (G67) of parameter No. 6000 can be set to 1 to specify that the alarm does not occur in this case.
- In a G66 block, no macros can be called. Local variables (arguments) are set, however.
- G66 needs to be specified before any arguments.
- No macros can be called in a block which contains a code such as a auxiliary function that does not involve movement along an axis.
- Local variables (arguments) can only be set in G66 blocks. Note that local variables are not set each time a modal call is performed.

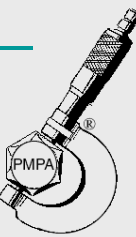
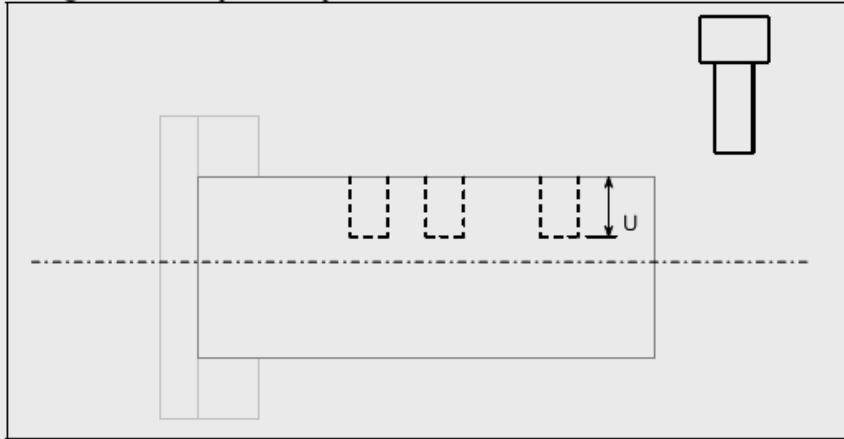
## NOTE

If M99 is specified in a block in which a call is performed, it is executed after the call is performed.

## Sample program

**T**

This program makes a groove at a specified position.



### - Calling format

```
G66 P9110 Uu Ff ;
```

U : Groove depth (incremental programming)

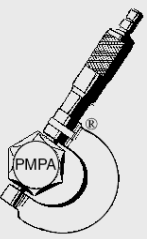
F : Cutting feed of grooving

### - Program that calls a macro program

```
O0003 ;  
G50 X100.0 Z200.0 ;  
S1000 M03 ;  
G66 P9110 U5.0 F0.5 ;  
G00 X60.0 Z80.0 ;  
Z50.0 ;  
Z30.0 ;  
G67 ;  
G00 X00.0 Z200.0 M05 ;  
M30 ;
```

### - Macro program (program called)

```
O9110 ;  
G01 U-#21 F#9 ;..... Cuts the workpiece.  
G00 U#21 ;..... Retracts the tool.  
M99 ;
```

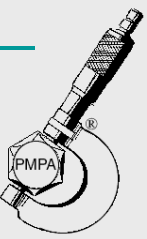


---

# Macro Program Examples

---

# Macro Examples: (Tool Life Frequency with Tool Change)



This example uses two tools of the same type. When the 1<sup>st</sup> tool has expired the machine starts using the 2<sup>nd</sup> tool.

Variables:

#510=Tool in Use (Machine Decision)

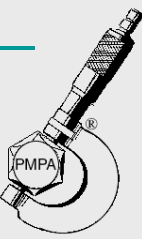
#511=Tool Life Expectancy (Operator Set)

#512=1<sup>st</sup> Tool Life Counter

#513=2<sup>nd</sup> Tool Life Counter

Once both tool counters have expired the counters will reset and an alarm will stop the machine with a tool change message.

# Macro Examples: (Tool Life with Tool Change)



O1204(PROGRAM)  
(VARIABLES TO SET BY OPERATOR)  
(#511= TOOL LIFE AMOUNT)  
(TOOL LIFE 1ST GROUP)  
IF[#512GE#511]GOTO30  
#510=1616  
GOTO100  
N30(2ND TOOL)  
IF[#513GE#511]GOTO881  
#510=1717

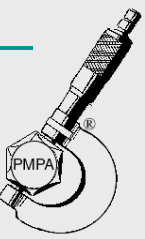
N100(MAIN PROGRAM)  
G00G40G18G99G20G97  
T#510(TOOL CALL )  
G0G99X.550Z.05M3S3000  
G1G42X.520Z.015F.005  
G1X.490Z0F.001  
G1X-.015  
G0Z-.05  
G28U0

(1ST TOOL)  
IF[#512GE#511]GOTO50  
#512=[#512+1] (ADD COUNT)  
GOTO60  
N50(2ND TOOL)  
#513=[#513+1] (ADD COUNT)  
N60

(RESET COUNT AND ALARMS)  
GOTO999(NO TOOLS EXPIRED)  
N881(1ST GROUP ALARM)  
#512=0(RESET 1ST COUNT)  
#513=0(RESET 2ND COUNT)  
#3000=1(GROUP 1 EXPIRED)

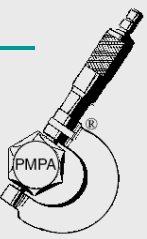
N999(PROGRAM END)  
M30





# Macro Examples: (Tool Life by Time Macro)

## Supplied by Caron Engineering



This macro requires the use of sub-program calls by M-code. This feature is set up in the custom macro parameters.

Parameter 6071-6079 correspond with programs O9001-O9009.

- 1) Command M201 after every T-code command (O9001 program)
- 2) At the end of the cutting sequence (before any T0) command M202 (O9002 program)

This program will accumulate time to the commanded T-code.

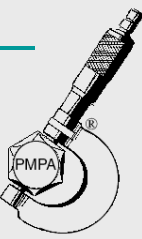
- 3) At the beginning and end of your main program command M203 (O9003 program)

This program will determine if any tools have expired.

- 4) If no preset value is set the tool life will not be measured.

# Macro Examples: (Tool Life by Time Macro)

## Supplied by Caron Engineering



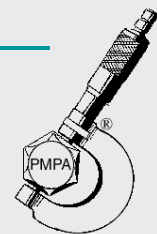
Macro Variables #501-#524 are used to preset and accumulate cutting time for up to 12 tools,

Life expectancy is set and measured in hours.

|           |             |                  |
|-----------|-------------|------------------|
| ■ Tool 1  | Preset #501 | Accumulator #502 |
| ■ Tool 2  | #503        | #504             |
| ■ Tool 3  | #505        | #506             |
| ■ Tool 4  | #507        | #508             |
| ■ Tool 5  | #509        | #510             |
| ■ Tool 6  | #511        | #512             |
| ■ Tool 7  | #513        | #514             |
| ■ Tool 8  | #515        | #516             |
| ■ Tool 9  | #517        | #518             |
| ■ Tool 10 | #519        | #520             |
| ■ Tool 11 | #521        | #522             |
| ■ Tool 12 | #523        | #524             |

# Macro Examples: (Tool Life by Time Macro)

## Supplied by Caron Engineering



This shows the correct parameter settings for this Macro Routine.  
M201=O9001, M202=O9002, and M203=O9003.

PARAMETER 01002 N00000

|       |                       |       |              |
|-------|-----------------------|-------|--------------|
| 06064 | MACRO CALL DPG (9044) | 06075 | 0            |
|       | 0                     | 06076 | 0            |
| 06065 | MACRO CALL DPG (9045) | 06077 | 0            |
|       | 0                     | 06078 | 0            |
| 06066 | MACRO CALL DPG (9046) | 06079 | 0            |
|       | 0                     | 06080 | MACRO CALL M |
| 06067 | MACRO CALL DPG (9047) |       | 0            |
|       | 0                     | 06081 | 0            |
| 06068 | MACRO CALL DPG (9048) | 06082 | 0            |
|       | 0                     | 06083 | 0            |
| 06069 | MACRO CALL DPG (9049) | 06084 | 0            |
|       | 0                     | 06085 | 0            |
| 06071 | SUB CALL M            | 06086 | 0            |
|       | 201                   | 06087 | 0            |
| 06072 | 202                   | 06088 | 0            |
| 06073 | 203                   |       |              |
| 06074 | 0                     |       |              |

A>^

EDIT \*\*\*\* \* \* \* \* 04:04:38 NC2

|        |     |        |     |       |       |        |        |   |  |
|--------|-----|--------|-----|-------|-------|--------|--------|---|--|
|        |     |        |     |       |       |        |        |   |  |
| PARAME | TER | DIAGNO | SIS | SERVO | GUIDE | SYSTEM | (OPRT) | + |  |

# Macro Examples: (Tool Life by Time Macro)

Supplied by Caron Engineering



## START TIMER

```
O9001  
(M201 START  
TIMER)  
#105=0  
#106=0  
#107=0  
#3002=0  
#105=#3002  
M99
```

## MEASURE TIME OF CUTTING PROCESS

```
O9002  
(M202 ACCUMULATE TIME)  
#106=#3002  
#107=#106-#105 (TIME FROM M201 TO M202)  
#103=FIX[#4120/100] (FIX T-CODE TO INTEGER)  
IF[#103EQ0]GOTO5 (IF T-CODE IS ZERO DON'T USE)  
IF[#103EQ#0]GOTO5 (IF T-CODE IS NULL DON'T USE)  
#102=#103*2 (#102=T-CODE INTEGER * 2)  
#100=500+#102 (DETERMINE ACCUMULATOR #)  
#[#100]=#[#100]+#107 (ADD TIME TO ACCUMULATOR)  
N5M99
```

# Macro Examples: (Tool Life by Time Macro)

Supplied by Caron Engineering



O9003 (M203 TOOL LIFE ALARMS)  
(TOOL 1)

IF[#501EQ0]GOTO20 (IF PRESET IS ZERO SKIP)

IF[#501EQ#0]GOTO20 (IF PRESET IS NULL SKIP)

IF[#502LT#501]GOTO20 (IF ACCUMULATOR IS LESS THAN PRESET GOTO NEXT TOOL)

#502=0 (SET ACCUMULATOR TO ZERO)

#3000=1(HD1 TOOL 1 LIFE EXPIRED) (ALARM)  
(TOOL 2)

N20IF[#503EQ0]GOTO30

IF[#503EQ#0]GOTO30

IF[#504LT#503]GOTO30

#504=0

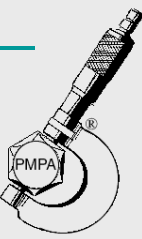
#3000=2(HD1 TOOL 2 LIFE EXPIRED)  
(TOOLS 3-12)

N999M99

%

# Macro Examples: (Tool Life by Time Macro)

Supplied by Caron Engineering



Part Program Format:

O1234

M203(TOOL LIFE CHECK)

G0G80G99

T0101

G0G99X1.0Z0M3S1000

M201(TIME RESET)

(CUTTING PROCESS)

M202(MEASURE TIME)

G28U0

T0

T0303

G0G99X1.0Z0M3S1000

M201(TIME RESET)

(CUTTING PROCESS)

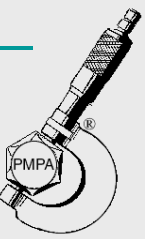
M202(MEASURE TIME)

G28U0

T0

M203(TOOL LIFE CHECK)

M30





# Macro Examples: M-Code Sub Program



This program uses a system variable to calculate on and off time for a chip conveyor.

```
O9005(M2900 CONVEYOR ON-OFF)
(SET PARA 6075 TO 2900)
(AT BEGINNING OF PART PRG.)
(COMMAND THE FOLLOWING TWO LINES)
(#3001=0)
(M#120)
(COMMAND M2900 AT END OF PART PRG)
(SET #525 OFF TIME MINUTES)
(SET #527 ON TIME MINUTES)
```

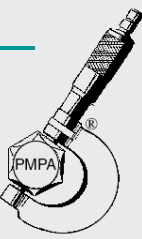
```
(OFF TIME DECISION)
IF[#526GE#525]GOTO201
#120=291
#526=[[#3001/1000/60]+#526]
GOTO299
```

```
N201(ON TIME DECISION)
IF[#528GE#527]GOTO202
#120=290
#528=[[#3001/1000/60]+#528]
GOTO299
```

```
N202(RESET TIMERS)
#526=0(OFF TIMER RESET)
#528=0(ON TIMER RESET)
```

```
N299(END)
M99
```

# Macro Examples: M-Code Sub Program



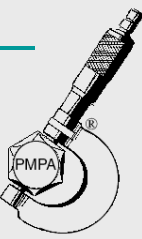
The program part program sets the timer to zero, commands the chip conveyor and timer sub-routine.

```
O1234(PART PROGRAM)
#3001=0(ZERO MILLI SECOND TIMER)
M#120(CHIP CONVEYOR ON/OFF)
```

```
(PART PROGRAM)
```

```
M2900(CALLS PROGRAM O9005)
M30
```

# Macro Examples: Tool/Offset Change Macro



This macro example alternates between two roughing tools for 100 cycles.

It will then generate a tool change alarm for the two roughing tools.

It also subtracts .001" from the finish tool offset every 10 parts for 100 cycles.

It will then generate a tool change alarm for the finish tool.

# Macro Examples: Tool/Offset Change Macro



```
%  
O1234(TEST ALTERNATE TOOL MACRO)  
(ADJUST FINISH TOOL OFFSET)  
(9/30/2012 REV 1A)
```

```
N20 (FRONT FACE & ROUGH TURN)
```

```
IF[#523EQ0]THEN#505=2323
```

```
IF[#523EQ1]THEN#505=2222
```

```
M03 S3000 P1 G00 Z0.0 T#505
```

```
#522=[#522+1]
```

```
X0.83
```

```
G01 X-0.04 F0.004
```

```
Z-0.04 F0.08
```

```
G41 X0.62
```

```
Z0.748 F0.004
```

```
X0.742
```

```
U0.016 W0.008
```

```
G40 G00 X4.7244 W0.0 T0
```

```
IF[#523EQ0]GOTO21
```

```
IF[#523EQ1]GOTO23
```

```
N21#523=1
```

```
GOTO25
```

```
N23#523=0
```

```
N25
```

**(#523 is the toggle counter for selecting the tool)**

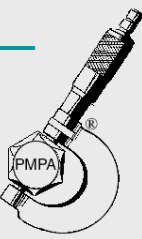
**(First Rough Tool Number)**

**(Second Rough Tool Number)**

**(Tool Call)**

**(TOOL LIFE COUNTER)**

# Macro Examples: Tool/Offset Change Macro



N30(FINISH TURNING)

M03 S3000 P1 G00 Z0.0T2121

#521=[#521+1]

IF[#521LT10]GOTO38

IF[#521EQ10]THEN#100=#2021

#101=[#100-.001]

#2021=#101

#521=0

N38X0.83

G01 X-0.04 F0.004

Z-0.04 F0.08

G41 X0.458

G01 X0.6 Z0.031 F0.004

Z0.75

X0.742

X0.83 W0.044

G40 G00 X4.7244 W0.0 T0

(TOOL LIFE COUNTER)

(How many parts to make before you change the offset)

(Wear offset of Tool 21 in X-Axis)

(How much to change the offset)

(AFTER CUT-OFF)

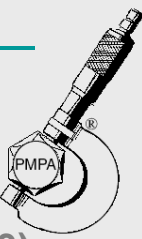
M95

/M92(BAR CHANGE)

M96

M97

# Macro Examples: Tool/Offset Change Macro



IF[#522LT100]GOTO9021

(TOOL LIFE TOTAL COUNT BOTH TOOL 22 & TOOL 23)

#522=0

G28U0

T0

**#3000=1(CHANGE INSERT #T22& #T23) (ALARM GENERATED)**

N9021

IF[#521LT100]GOTO9022

(TOOL LIFE TOTAL COUNT FOR TOOL 21)

#521=0

G28U0

T0

**#3000=1(CHANGE INSERT #T21) (ALARM GENERATED)**

N9022

N99M599

#501=0

M30

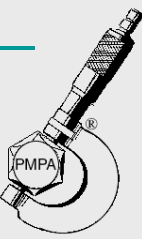
%

# Custom Macro and Probing



- The most common use for probing on a CNC machine is to determine part location for machining.
- Probes can also be used to measure features.
- When selecting a probe for your machine it is very important to work with the supplier to determine what your software requirements are.
- Most vendors will have a standard probing software package, but often these may need to be customized to suit your needs.
- You will also need to determine the control options required. (High Speed Skip, Additional Macro Variables, Work Offsets, Ect.)

# Custom Macro and Probing



The probe is basically a spring loaded stylus with an electronic switch. The machine moves the probe at a specified feed rate with a skip signal motion (G31).

Once the switch is tripped the machine motion stops. Now machine coordinates can be read to macro variables and decisions and calculations made accordingly.

Example:

G0Z1.5;

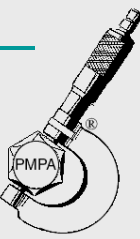
G31Z1.0F4.0;

The machine will travel from Z1.5 to Z1.0 at 4 IPM in High Speed Skip Mode. Once the probe trips the machine motion stops. At this time the actual Z location can be recorded.

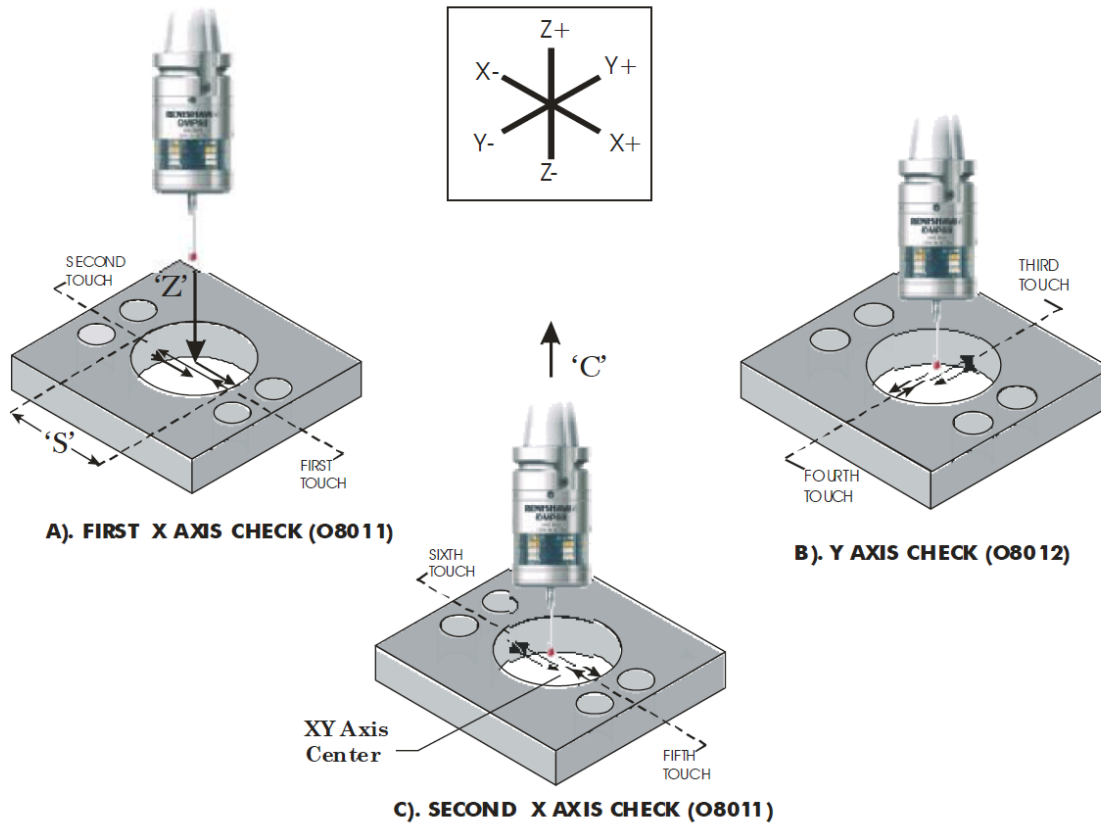


# Custom Macro and Probing

Caron Engineering Machining Center Probe Example:

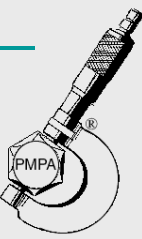


Program O8010 : HOLE SIZE and CENTER



# Custom Macro and Probing

## Caron Engineering Machining Center Probe Example:

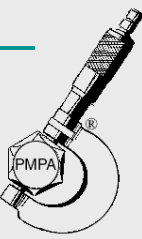


### Macro arguments for program O8010

|            |          |   |
|------------|----------|---|
| <b>C</b>   |          | an <b>ABSOLUTE</b> safe <b>RETRACT</b> position in the <b>Z-axis</b> .  |
| <b>(D)</b> | optional | the <b>cutter compensation offset number</b> used to cut the <b>HOLE</b> .<br>(SET TO 0 OR VACANT, IF NO OFFSET IS TO BE ADJUSTED)                              |
| <b>(E)</b> | optional | the +/- <b>true position tolerance</b> .<br>(If set to zero or vacant, true position is not checked.)   |
| <b>S</b>   |          | the <b>NOMINAL Hole Size</b> .  |
| <b>T</b>   |          | the <b>upper (+) tolerance</b> allowed from nominal size.   |
| <b>(U)</b> | optional | the <b>lower (-) tolerance</b> allowed from nominal size.<br>(If vacant, 'U is set to minus value of 'T'.)  |
| <b>(V)</b> | optional | the <b>extra work offset groups G54 P1-P48</b> to store the XY axes position.<br>(V = 1. to 48. for G54 P1 to P48; set V = 0 or #0, if no offset is to be set.) |
| <b>(W)</b> | optional | the <b>work offset groups G54 to G59</b> to store the XY axes position.<br>(W = 1. to 6. for G54 to G59; set W = 0 or #0, if no offset is to be set.)           |
| <b>Z</b>   |          | the <b>ABSOLUTE Z-axis depth</b> to probe the <b>Hole</b> .   |

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## Caron Engineering Machining Center Probe Example:



Programming example for O8010;

C=safe Z retract 1.0

S=Nominal hole size 1.4

T=Upper hole tolerance of .002

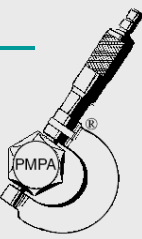
W=5<sup>th</sup> work offset update (G58)

Z=Depth inside hole to probe

|                                    |
|------------------------------------|
| T30 M6                             |
| G58 G90 G0 X0 Y0                   |
| M98 P8099                          |
| G90 G43 G31 H30 Z1. F80.           |
| G65 P8010 C1. S1.4 T.002 W5. Z-.25 |
| G91 G28 Z0                         |
| M98 P8098                          |
| M30                                |

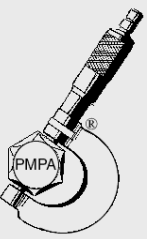
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## Caron Engineering Machining Center Probe Example:



During the probing cycle all of the calculated information is loaded to variables. Here it can be accessed for any additional calculations or decisions.

|      |     |   |
|------|-----|---|
| #102 | --- | The X-axis HOLE SIZE.                     |
| #112 | --- | The Y-axis HOLE SIZE.                     |
| #104 | --- | The AVERAGE HOLE SIZE.                    |
| #105 | --- | The HOLE SIZE ERROR                       |
| #106 | --- | The X-axis MACHINE Hole Center position.  |
| #107 | --- | The Y-axis MACHINE Hole Center position.  |
| #108 | --- | The X-axis ABSOLUTE Hole Center position. |
| #109 | --- | The Y-axis ABSOLUTE Hole Center position. |
| #118 | --- | The X and Y axes TRUE POSITION ERROR.     |

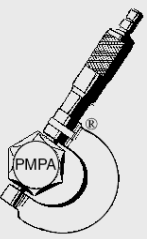


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# Open Discussion

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Questions?



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End

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Thank You